

Reconstruction of tangentially viewing images in a helical system

T. F. Ming, S. Ohdachi, Y. Suzuki
National Institute for Fusion Science
2013.09.06

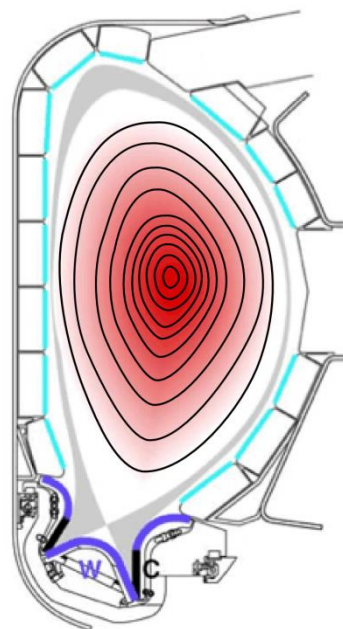
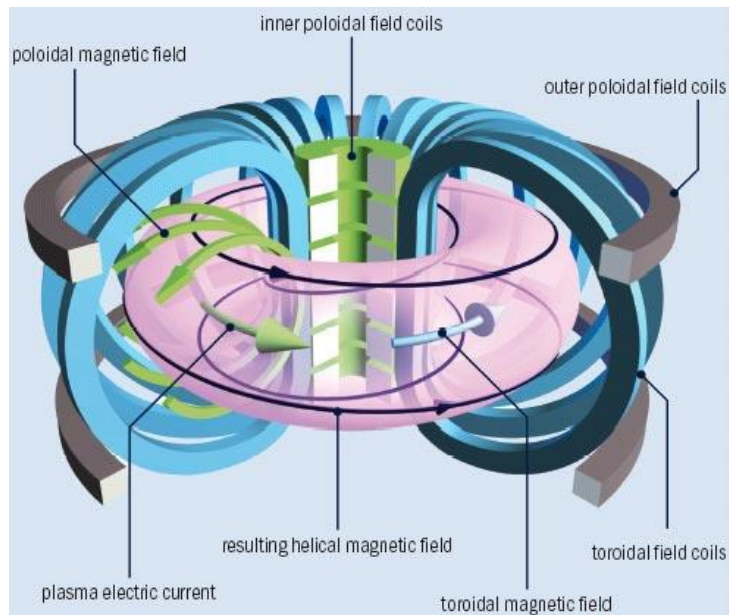


Outline

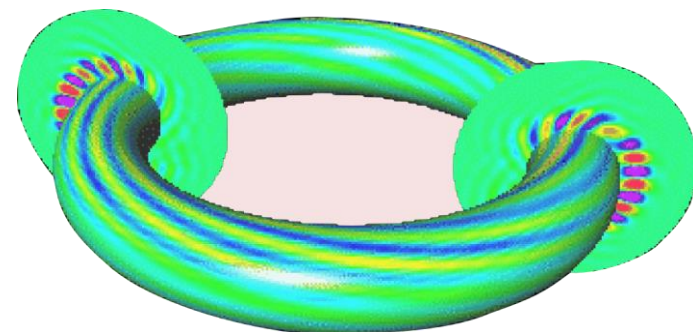
- **Background and motivations**
 - Merits of tangentially viewing imaging system
 - Tangentially viewing VUV imaging system in LHD
- **Image reconstructions**
 - Relation of line-integrated image and local emission profile
 - Construction of geometry matrix
 - One-dimensional array
 - Tangentially viewing imaging system
 - Synthetic image with a plausible emission profile
- **CT reconstruction by numerical tests with LHD configuration**
 - Iwama's type of P-T algorithm
 - Numerical test results
- **Experimental results**
 - Observation of the distorted emission profile caused by ELM event
- **Summary**



Background



MHD mode structure

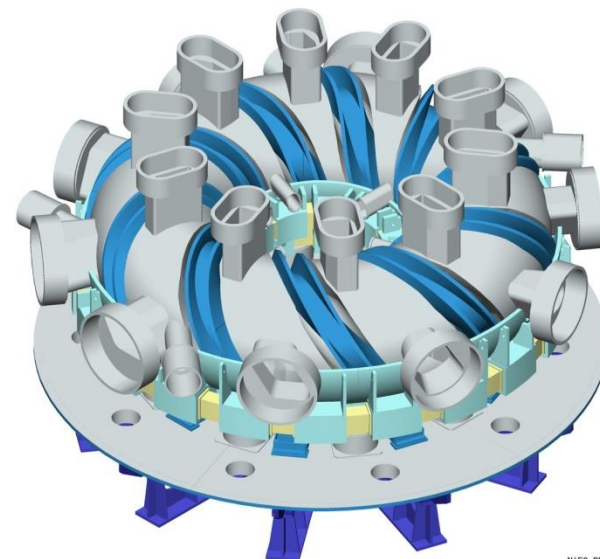
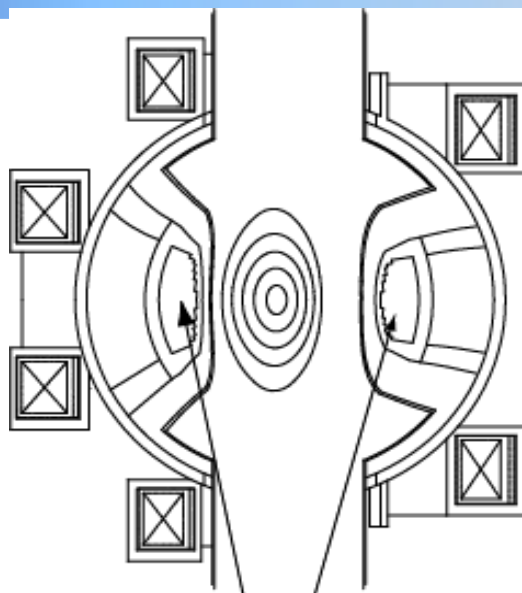
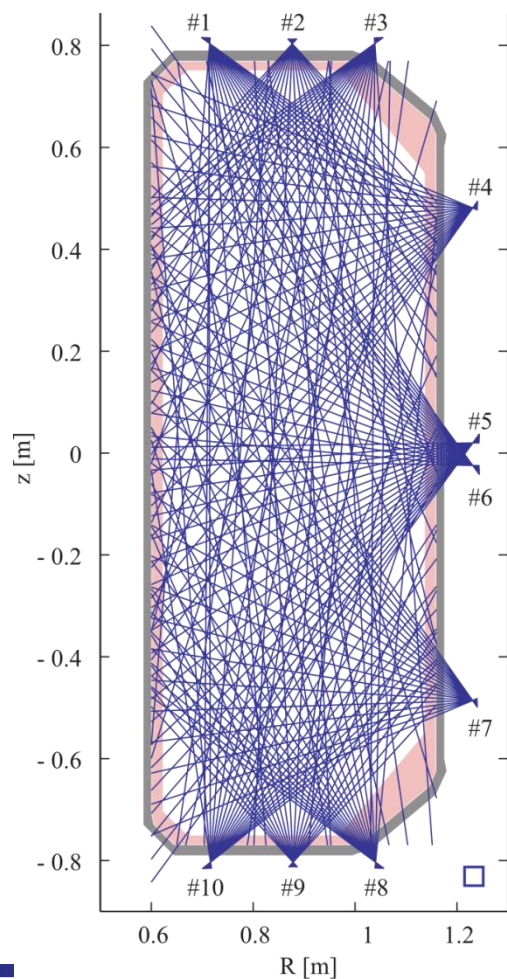


- Plasma is confined by a magnetic configuration produced by the combination of external coils and plasma current.
- Emissivity is approximately constant on each magnetic flux surface.
- Emission profile can be modified by MHD instabilities.



Easier installation of the tangentially viewing imaging system in LHD

J. Mlynar et al, PPCF(2003)

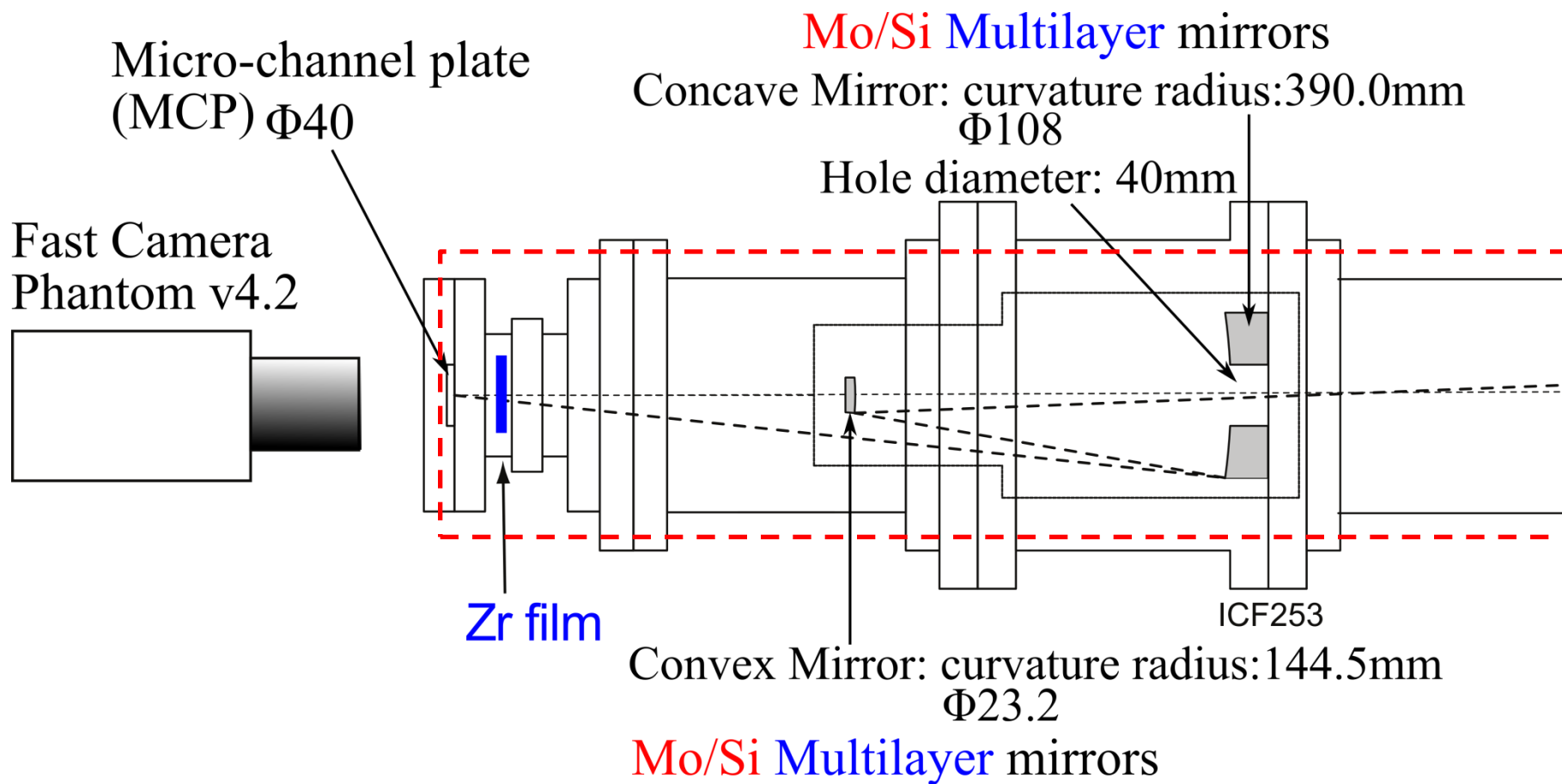


NIFS-PE381

- Successful tomographic reconstruction requires observations from different viewing angles.
- Viewing angles are restrained by the helical coils in LHD.



Schematic diagram of the VUV imaging system





Viewing field of VUV imaging system

- Whole system is installed at the 6-T port of LHD.
- The viewing fields of the VUV imaging system are restrained by the inner diameter of the tube.
- Part of the plasma volume is covered.

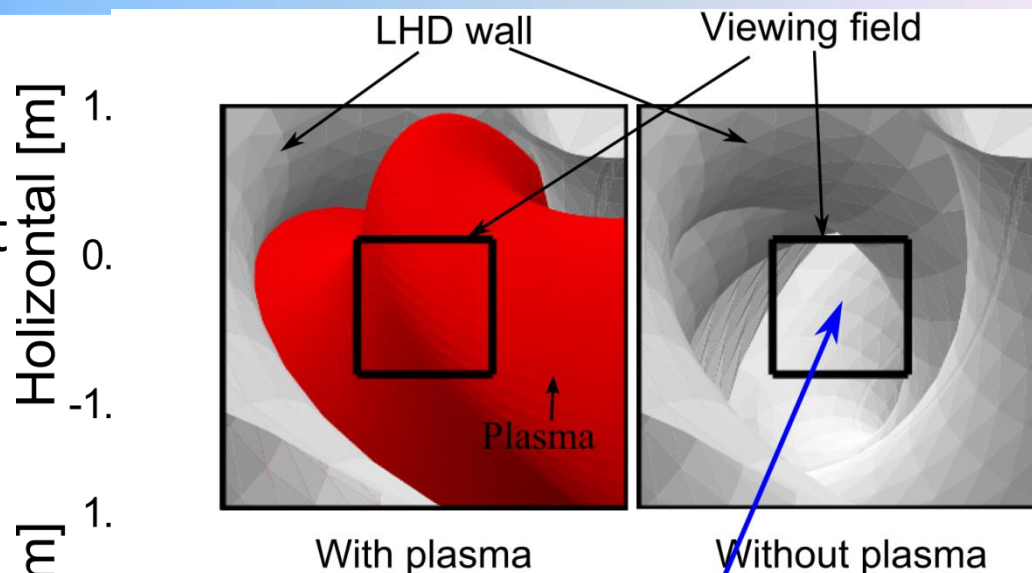
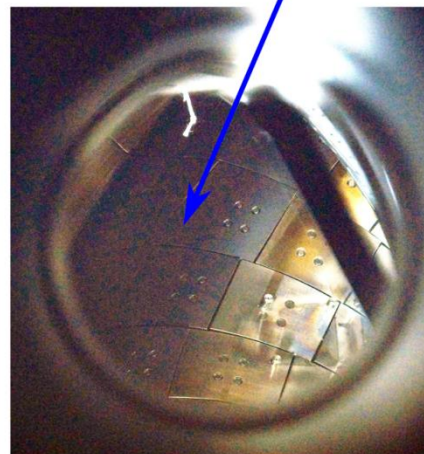


Image taken by a visible camera locating at the focus plane





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Relation between local emissivity and line-integrated measurements

For a 2D emission profile $E(x, y)$, the i 'th nonlocal measurement I_i can be described by

$$I_i = \int \int S_i(x, y) E(x, y) dx dy \quad (1)$$

Measurement

Weight function

Local emissivity

The discrete algebra form of (1) :

$$\mathbf{I} = \mathbf{S} \mathbf{E} \quad (2)$$

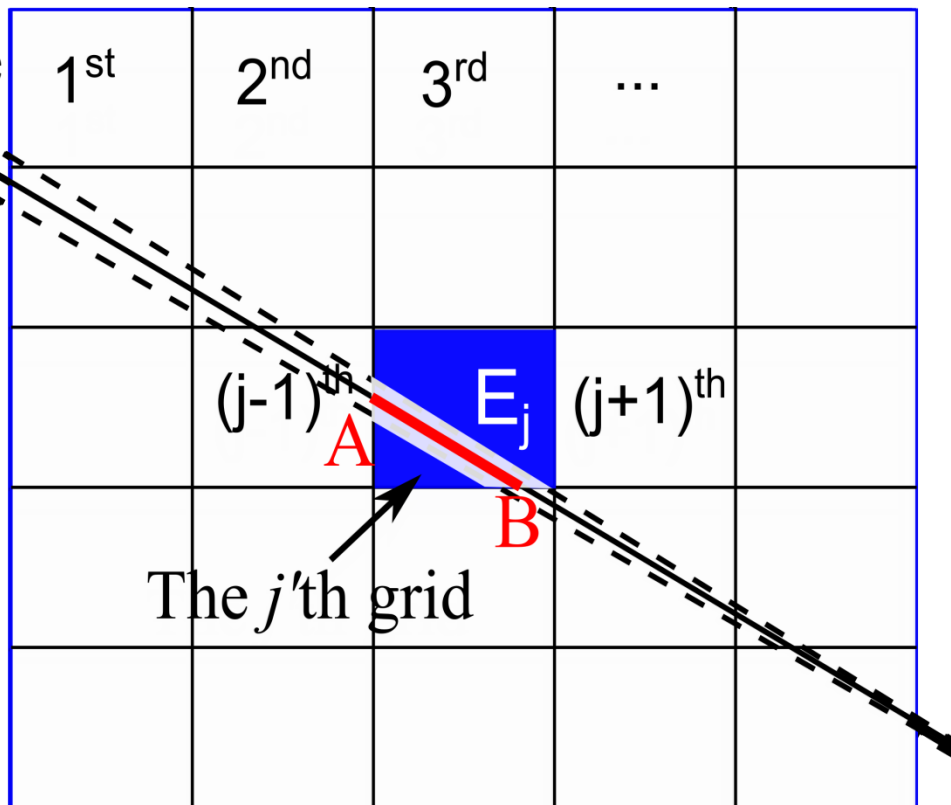
$$\text{with } \mathbf{I} = \begin{bmatrix} I_1 \\ \dots \\ I_M \end{bmatrix} \quad \mathbf{E} = \begin{bmatrix} E_1 \\ \dots \\ E_N \end{bmatrix}$$

S_{ij} describes the contribution to the i 'th measurement from the j 'th grid.



Construction of geometry matrix for 1D array measurement

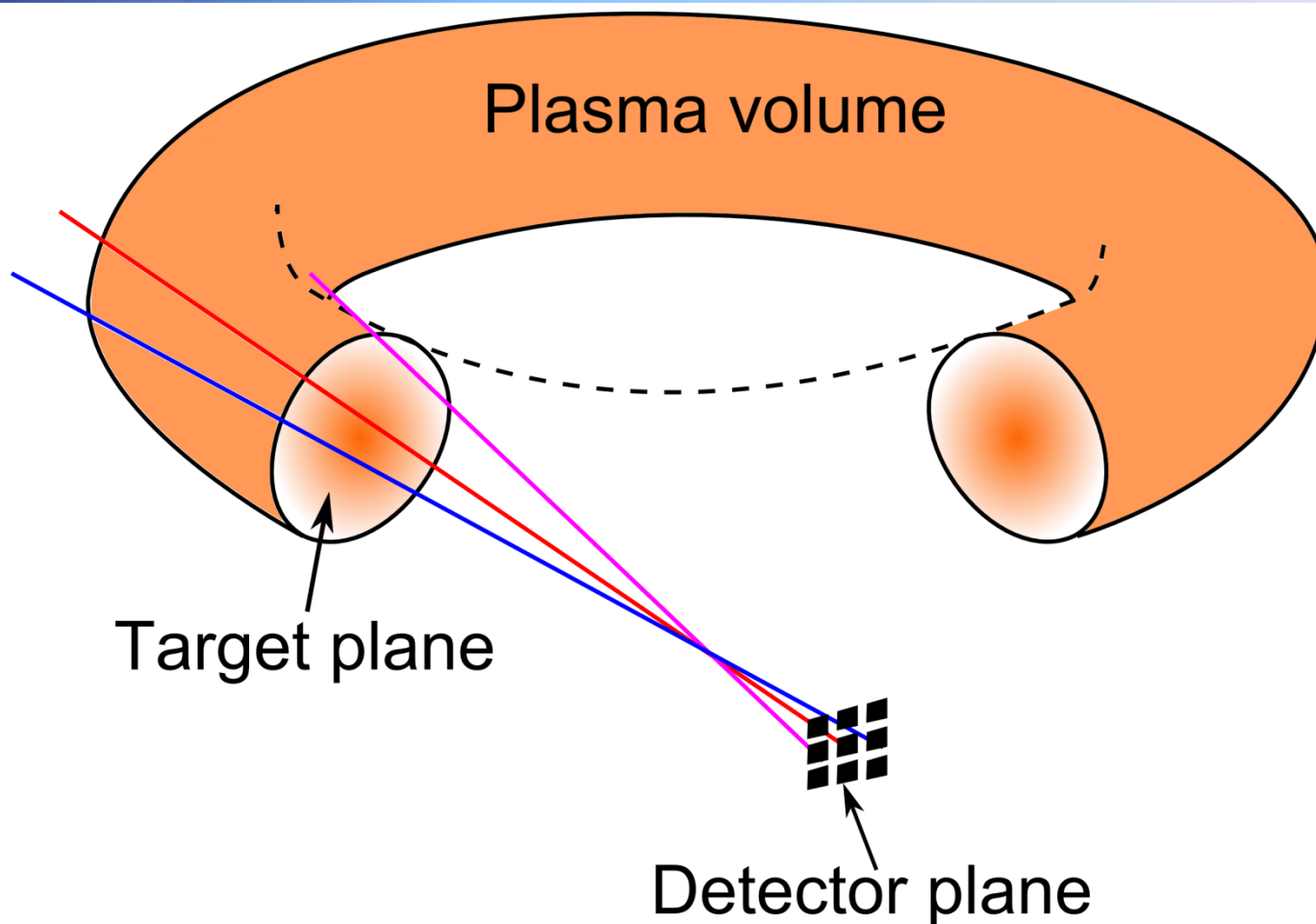
The i 'th sightline



$$S_{ij} \approx |AB|$$

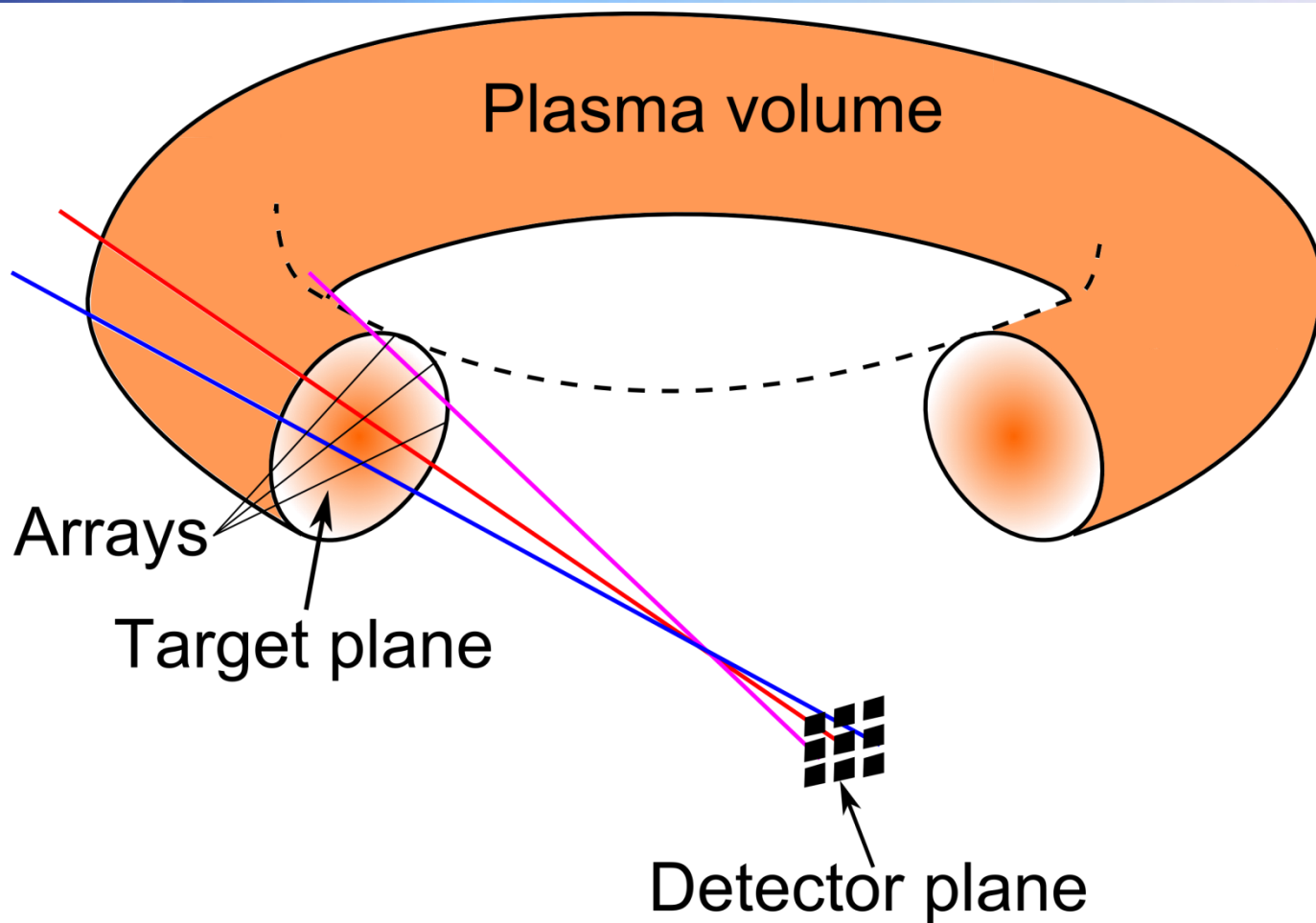


Schematic layout for tangential & array measurements



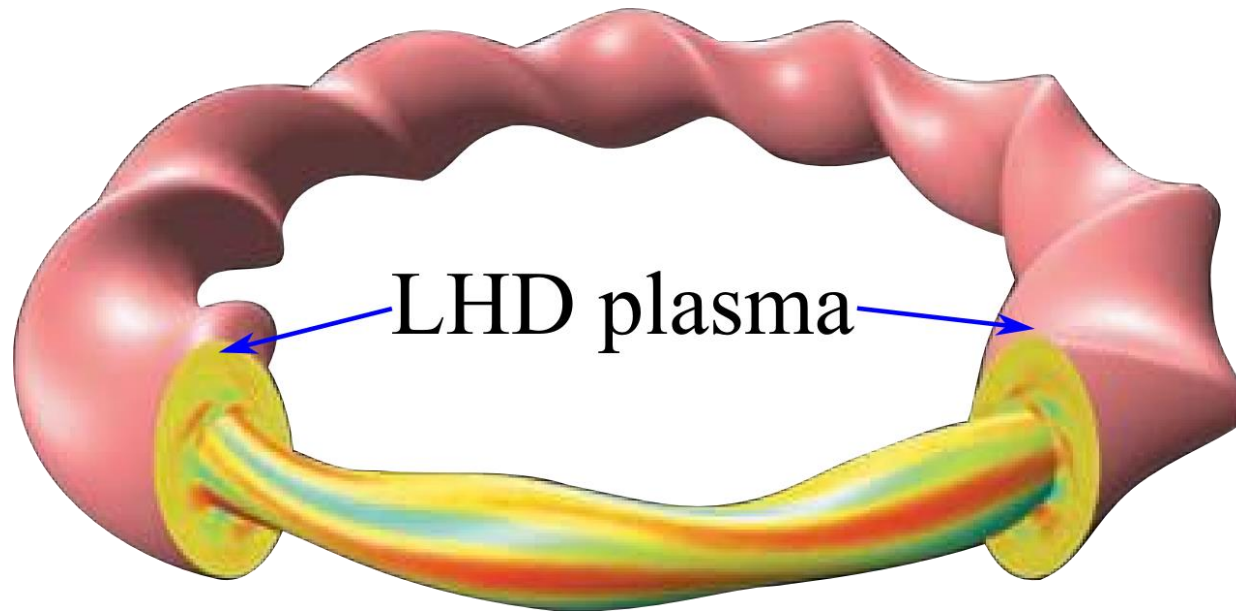


Schematic layout for tangential & array measurements





Complex plasma shape in helical device

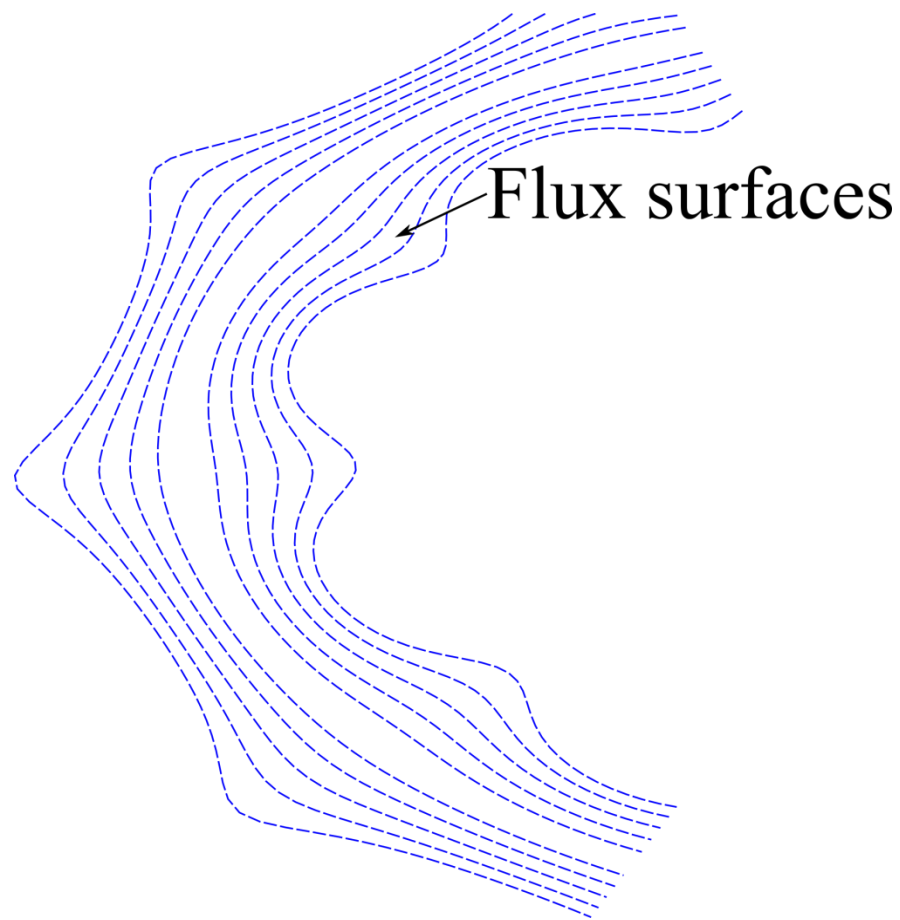


- Plasma volume is helically twisted in LHD.
- No axisymmetry exists in helical configuration.
- How to construct the geometry matrix for a tangentially viewing imaging system with a complex plasma shape?



Construction of geometry matrix for tangentially viewing camera

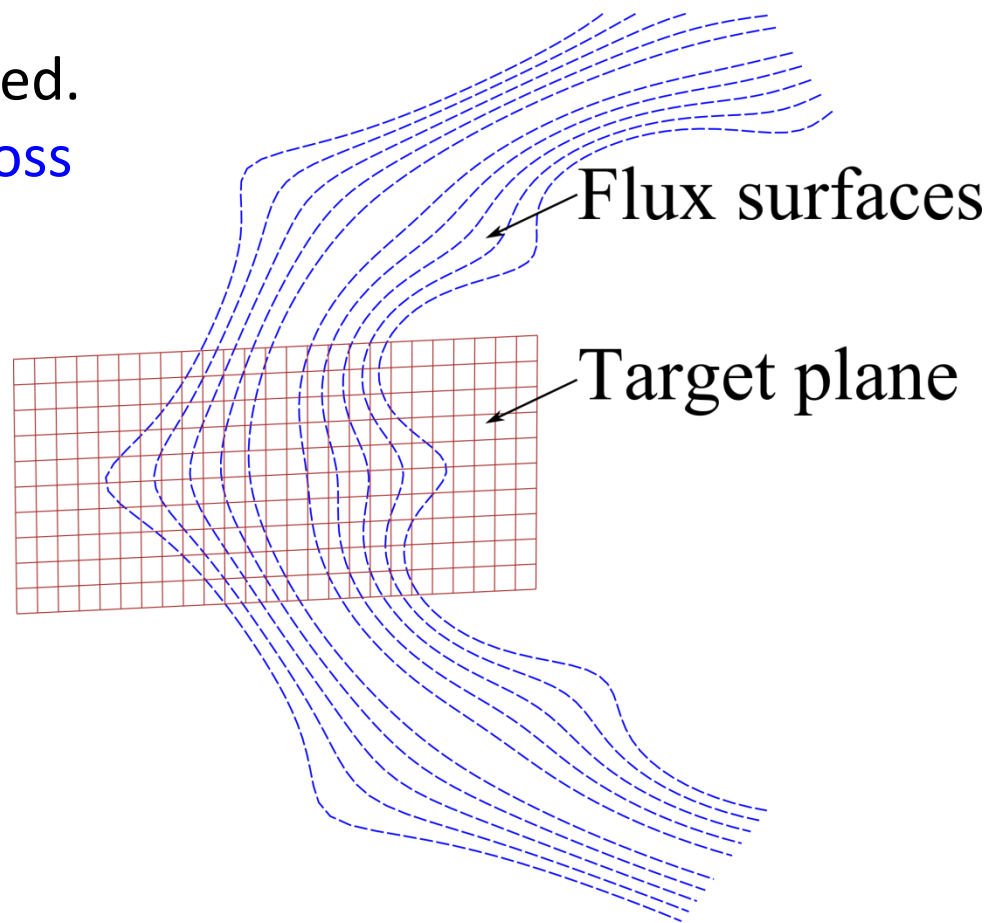
- The constant emissivity along the magnetic field line is assumed.





Construction of geometry matrix for tangentially viewing camera

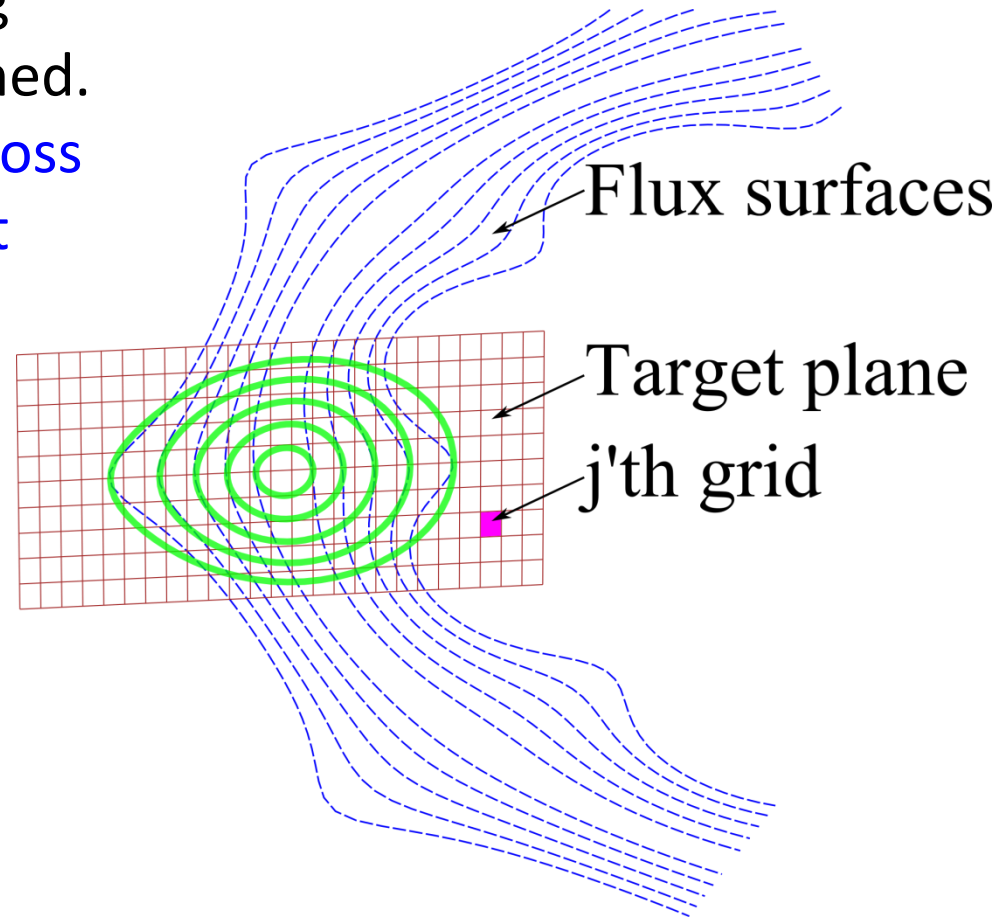
- The constant emissivity along the magnetic field line is assumed.
- The horizontally elongated cross section is selected as the target plane.





Construction of geometry matrix for tangentially viewing camera

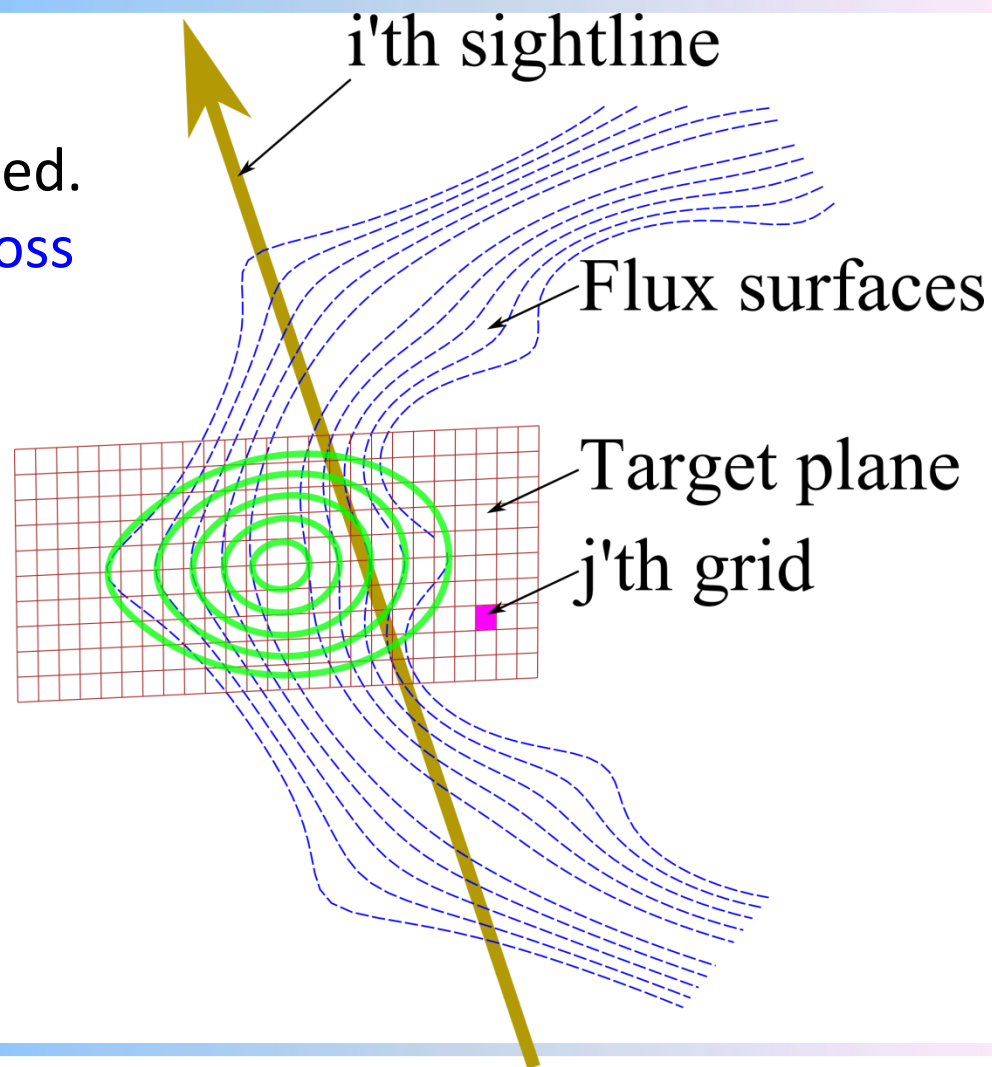
- The constant emissivity along the magnetic field line is assumed.
- The horizontally elongated cross section is selected as the target plane.





Construction of geometry matrix for tangentially viewing camera

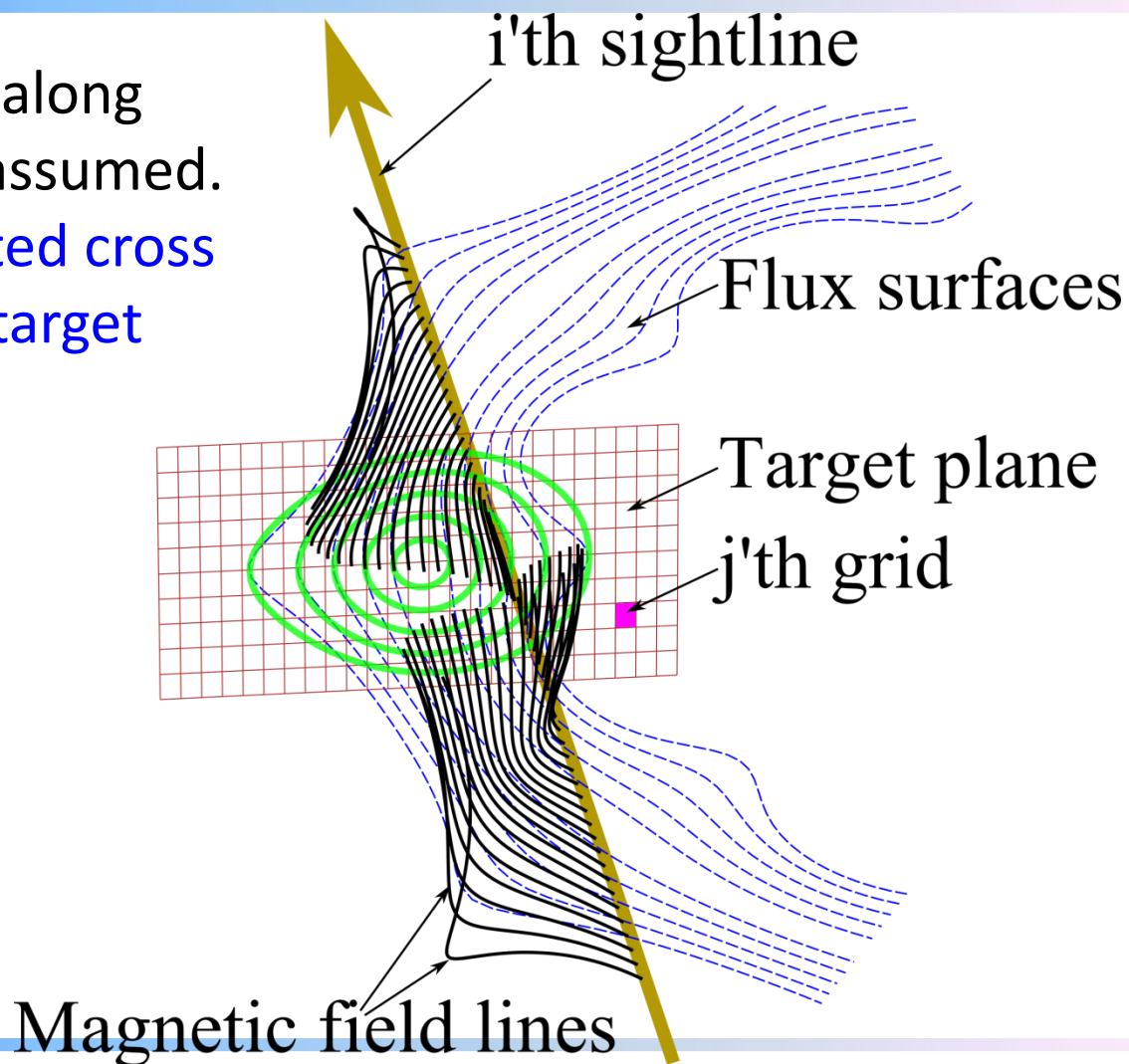
- The constant emissivity along the magnetic field line is assumed.
- The horizontally elongated cross section is selected as the target plane.





Construction of geometry matrix for tangentially viewing camera

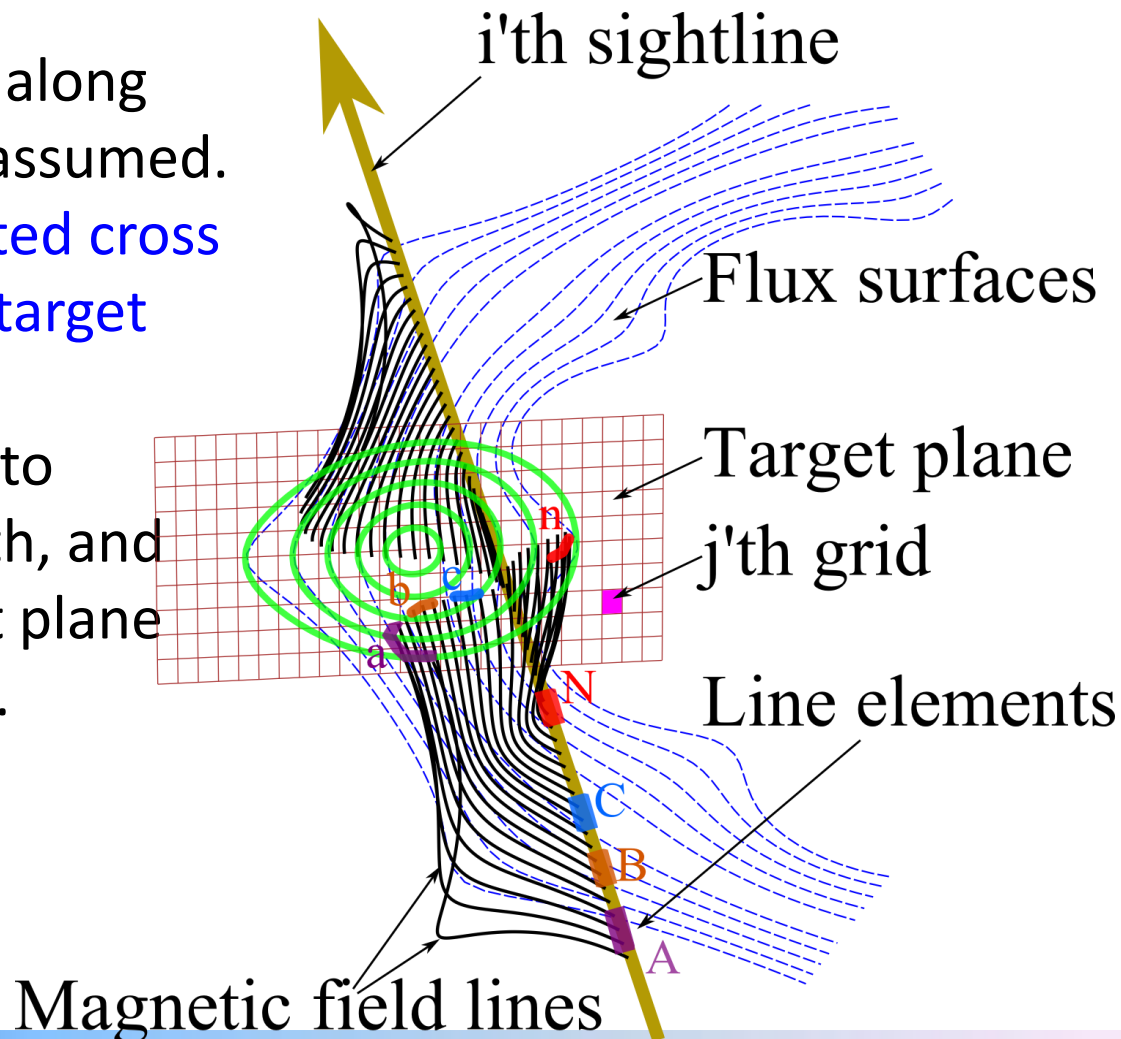
- The constant emissivity along the magnetic field line is assumed.
- The horizontally elongated cross section is selected as the target plane.





Construction of geometry matrix for tangentially viewing camera

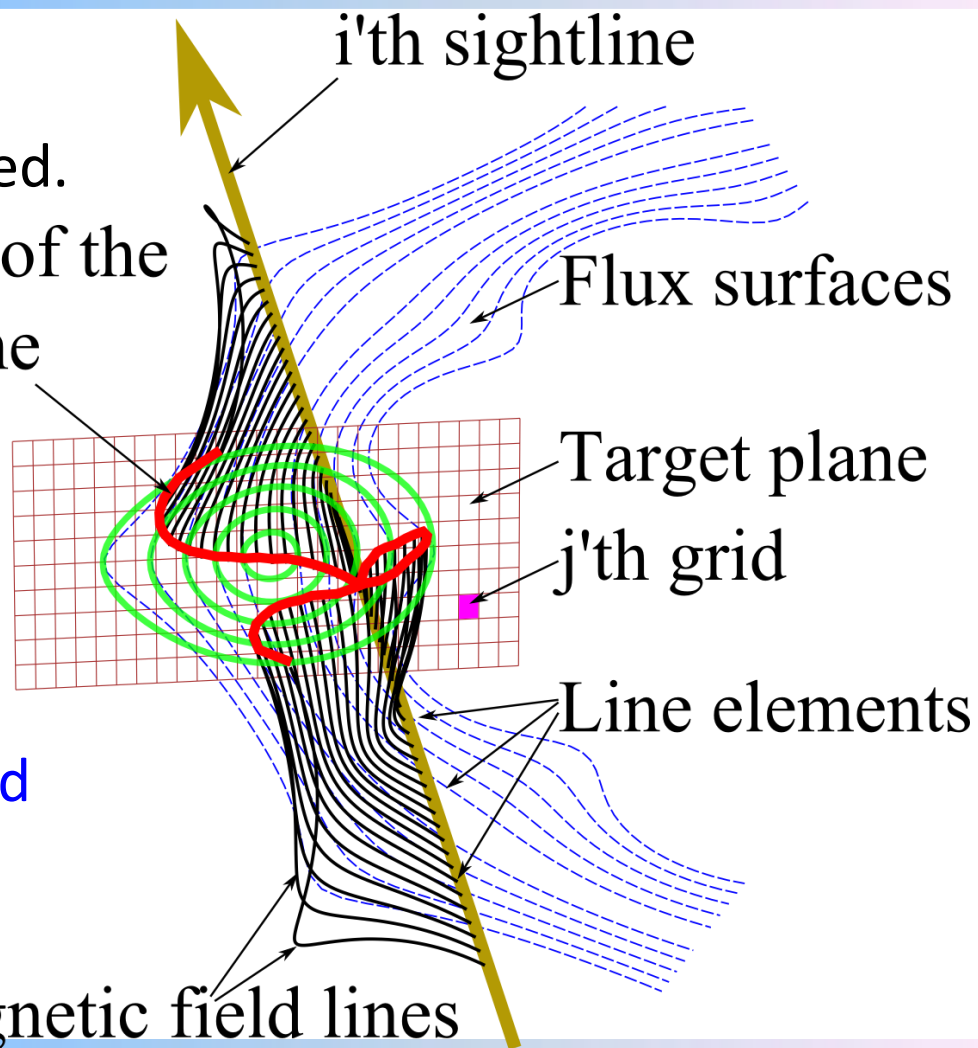
- The constant emissivity along the magnetic field line is assumed.
- The horizontally elongated cross section is selected as the target plane.
- Sightlines are divided into elements with same length, and projected on to the target plane along magnetic field lines.





Construction of geometry matrix for tangentially viewing camera

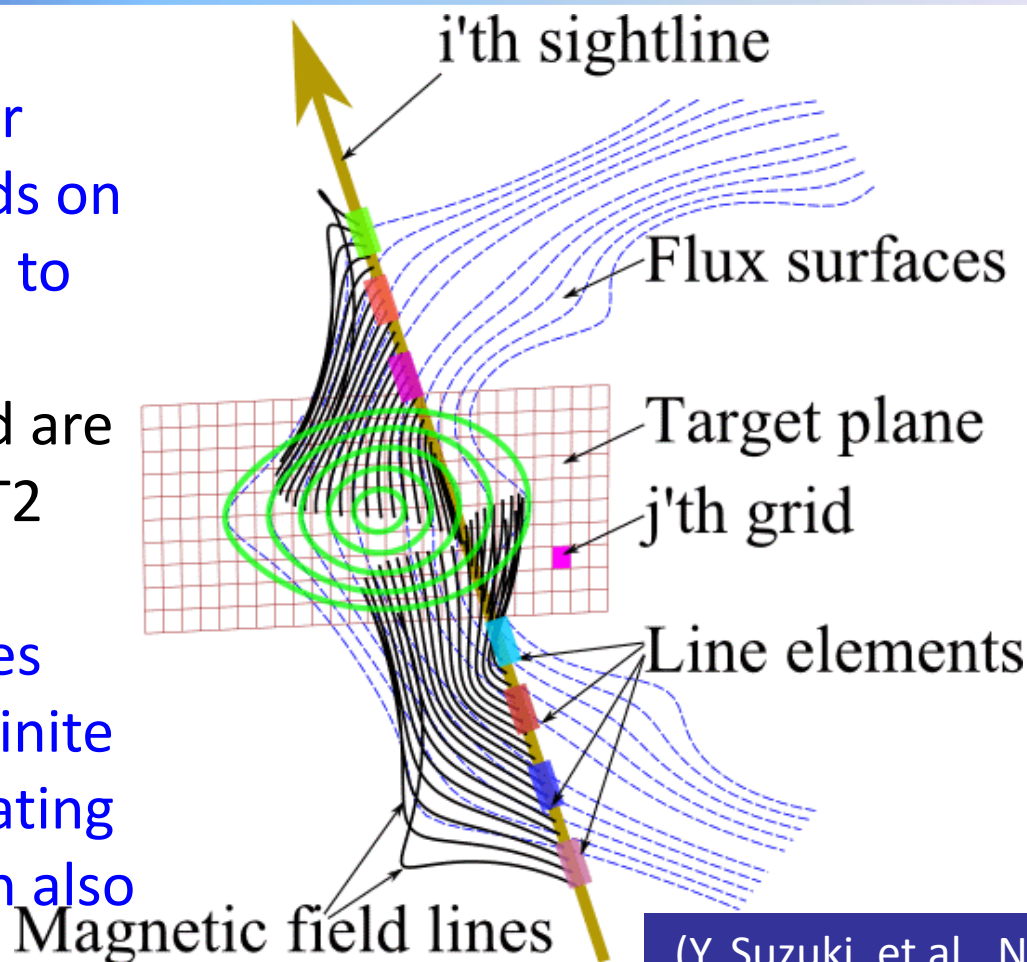
- The constant emissivity along the magnetic field line is assumed.
- The horizontally ϵ Projection of the section is selected i 'th sightline plane.
- Sightlines are divided into elements with same length, and projected on to the target plane along magnetic field lines.
- Equivalent sightline is obtained by relevant projection on the target plane.





Schematic process of sightline projections

- Line elements are projected forward or backward. It depends on the relative location to the target plane.
- The magnetic field are obtained using HINT2 equilibrium code.
- Magnetic field lines can be traced with finite beta. And those locating outside the LCFS can also be traced by HINT2.

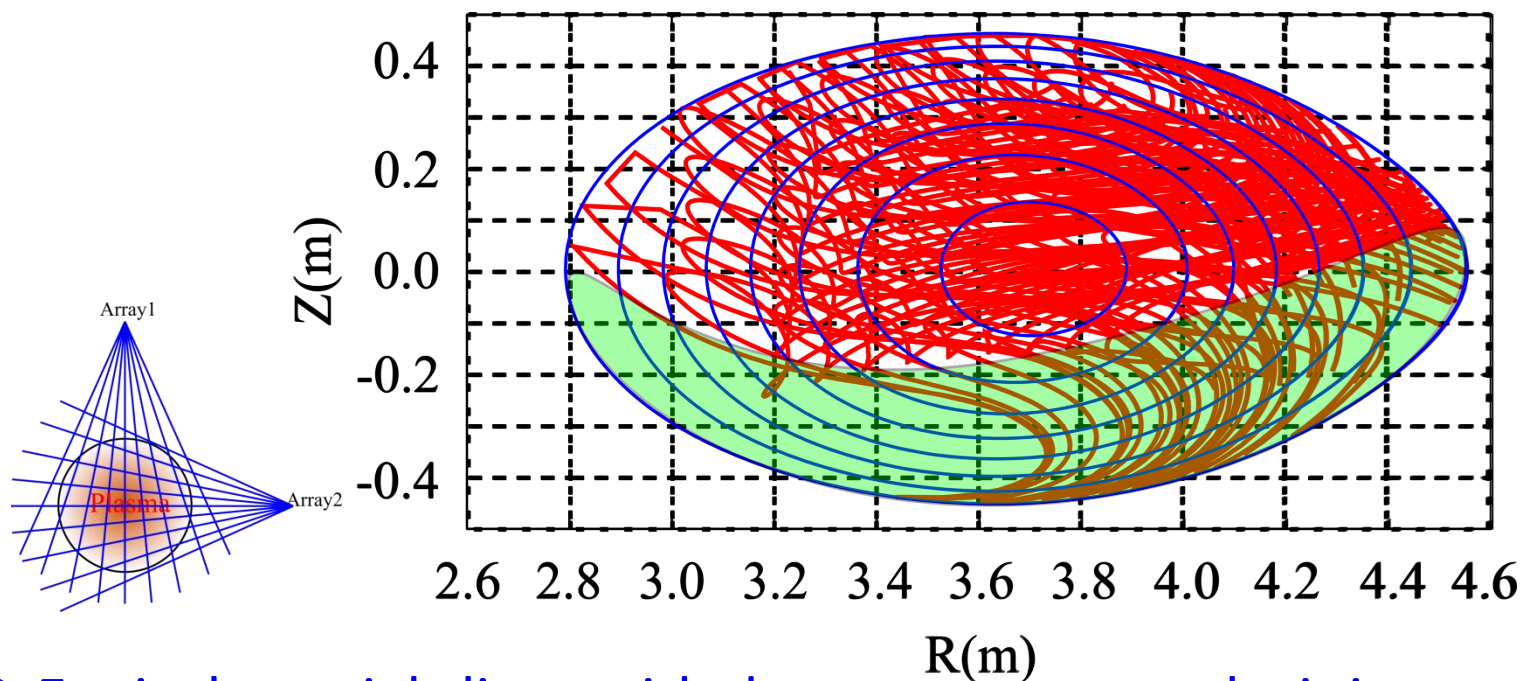


(Y. Suzuki, et al., Nucl. Fusion 46, L19 (2006),)



Sightline projections on target plane

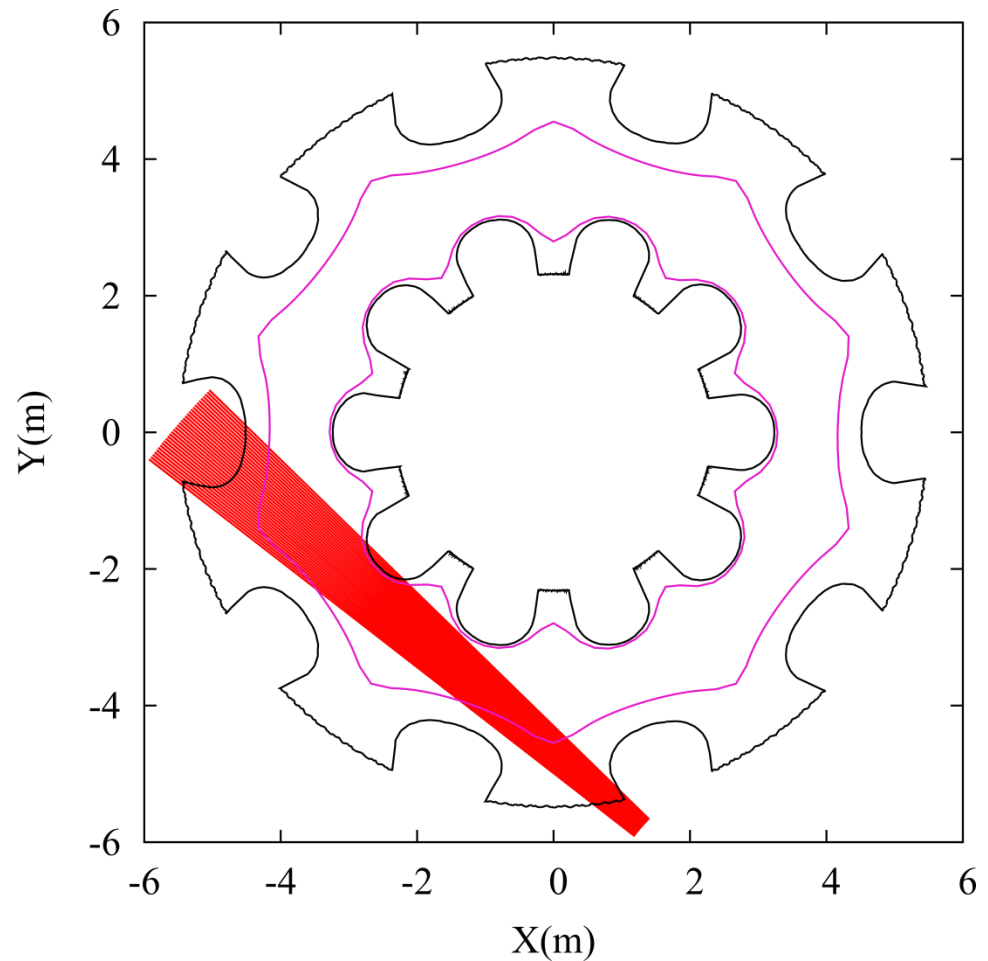
Equivalent sightlines on the target plane



- Equivalent sightlines with dense coverage make it possible to perform tomographic reconstruction.
- The sparse coverage on the lower part is due to the arrangement of the port.



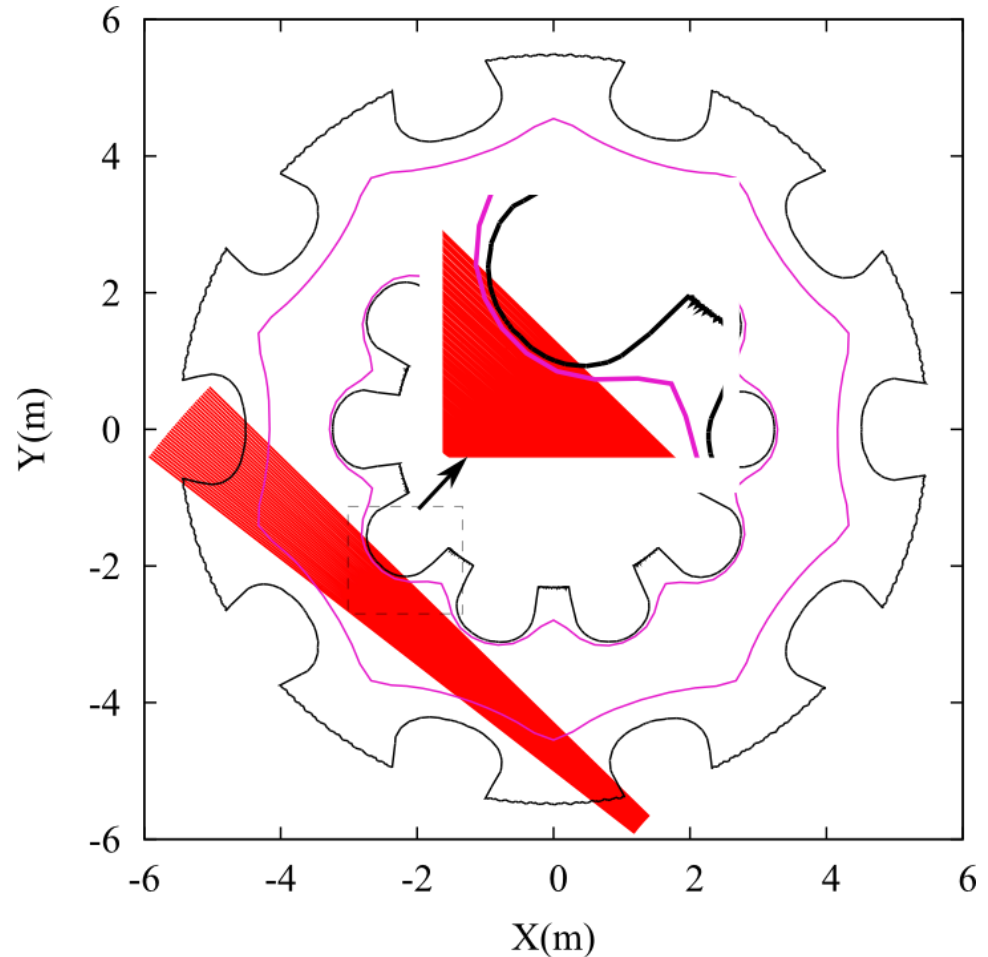
Intersection between sightlines and the first wall





Intersection between sightlines and the first wall

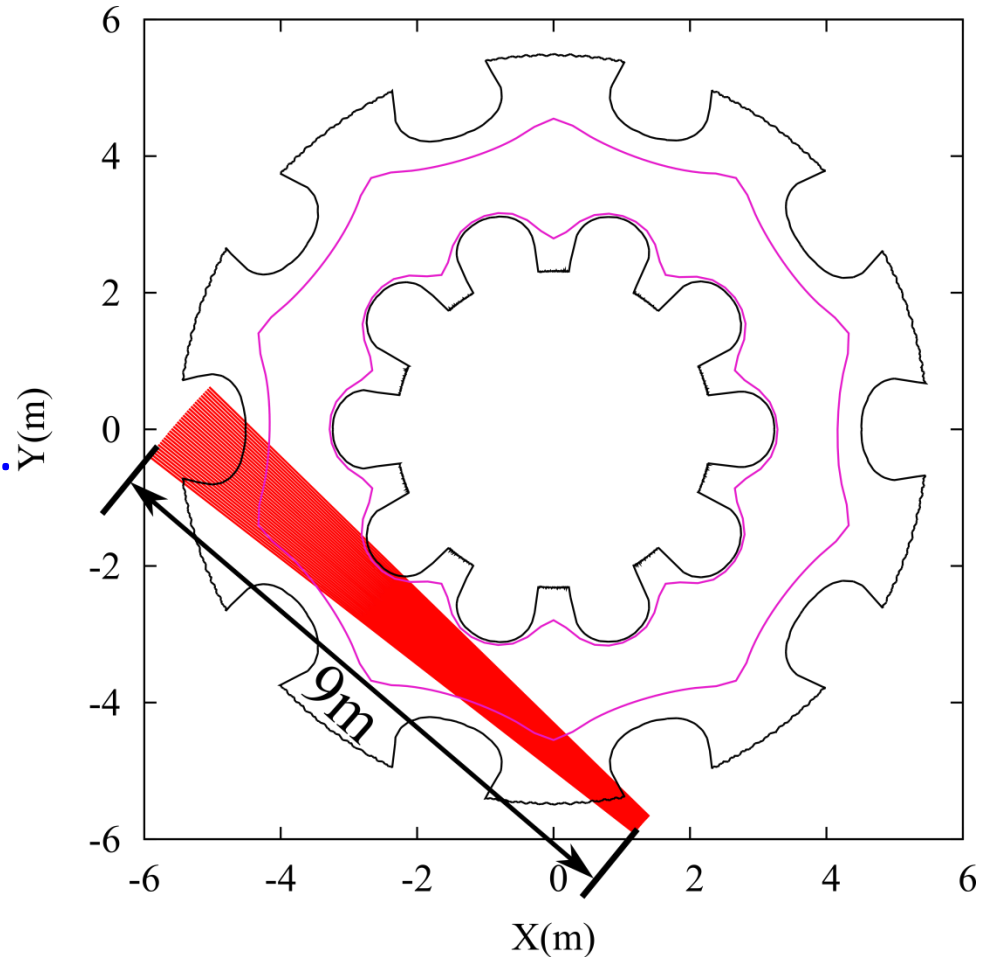
➤ Intersection between sightlines and the first wall might occur.





Intersection between sightlines and the first wall

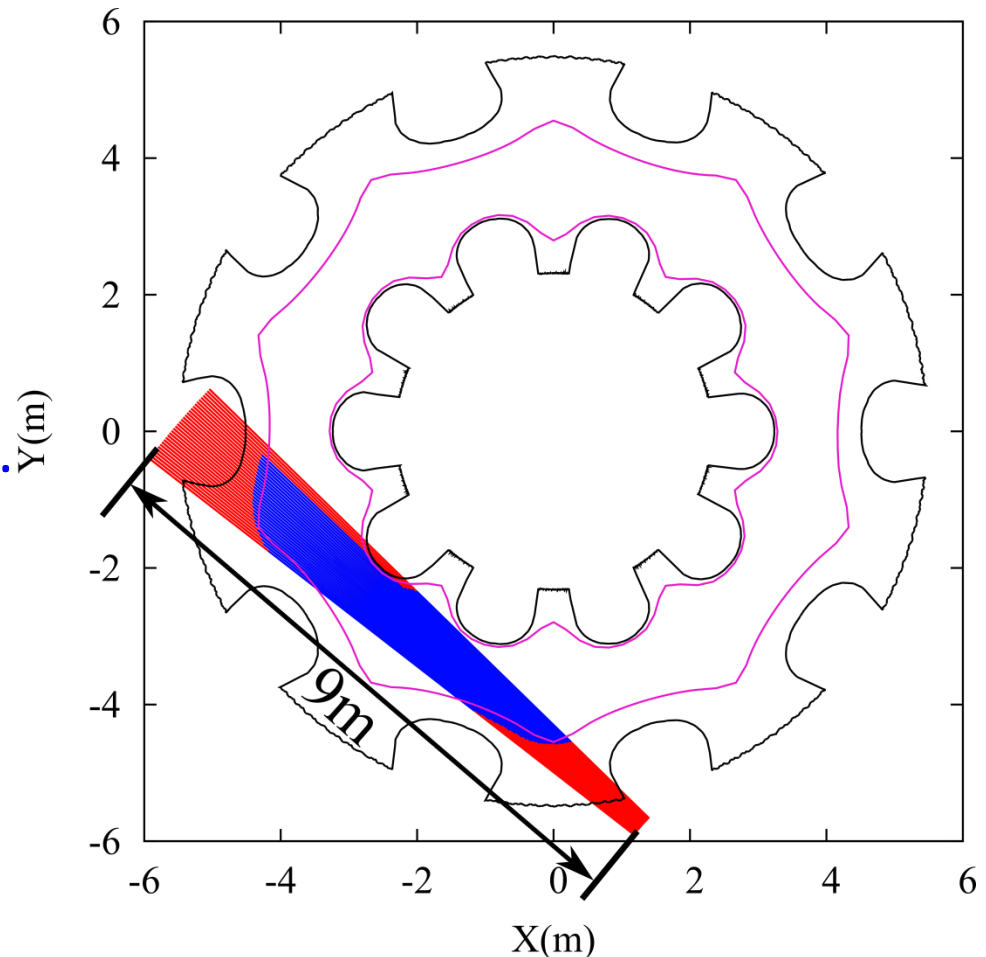
- Intersection between sightlines and the first wall might occur.
- Total length exceeds 9m for each sightline in the calculation.





Intersection between sightlines and the first wall

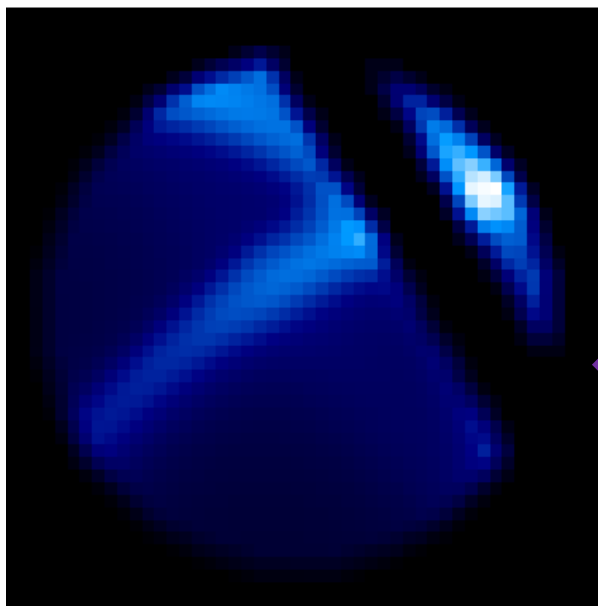
- Intersection between sightlines and the first wall might occur.
- Total length exceeds 9m for each sightline in the calculation.
- The surface of the first wall is simulated by small triangle plate elements. Calculation stops if the intersection occurred.





Local emissivity & line-integrated images

Line-integrated image

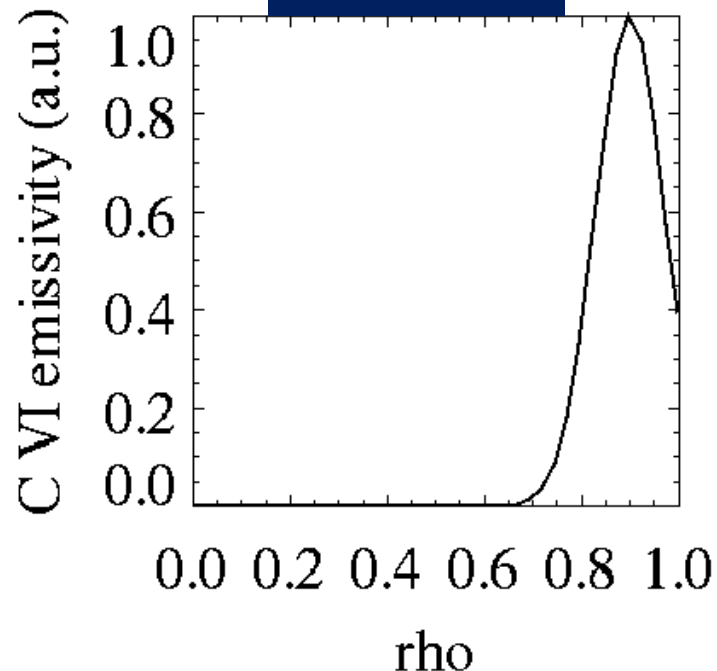


$$\mathbf{I} = \mathbf{S}\mathbf{E}$$

Synthetic image



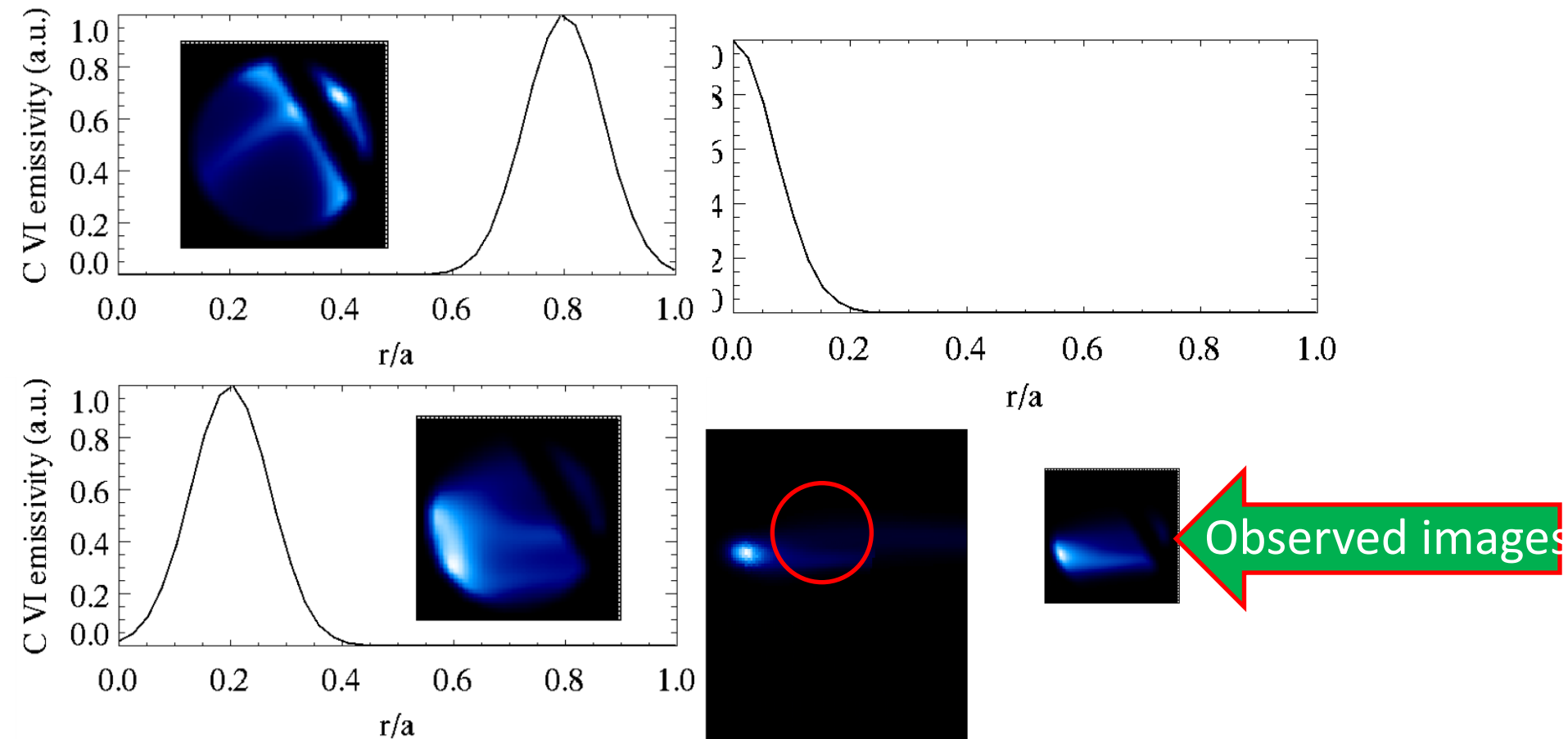
Emissivity



- Assuming local emission profile, relevant synthetic images could be made with the geometry matrix.
- Comparison of the experimental measured images with synthetic ones can be performed.



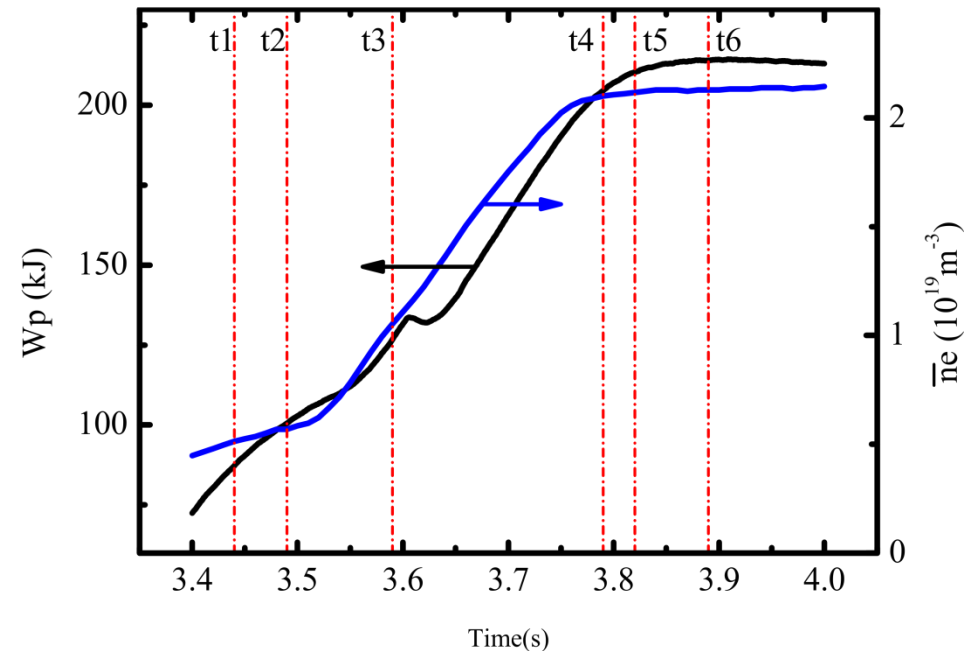
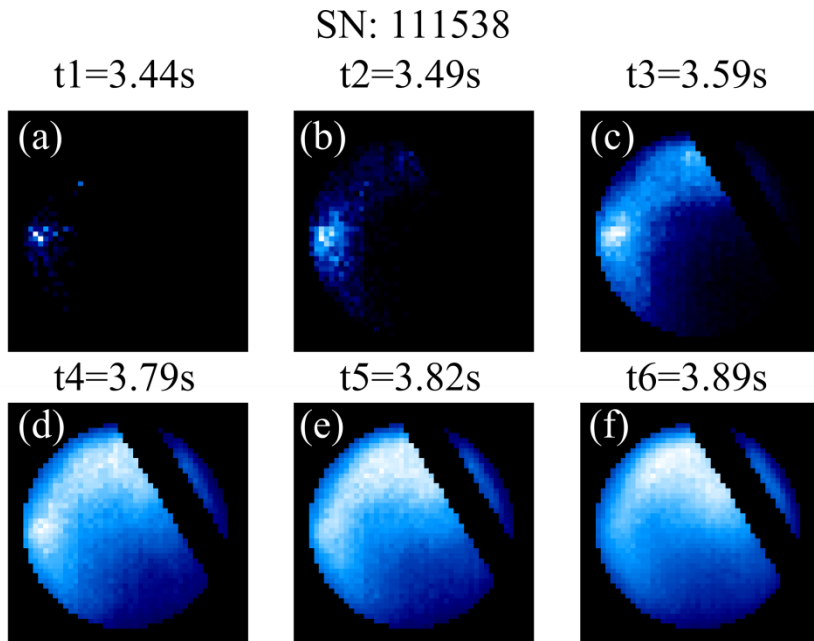
Synthetic images with different emission profiles



- Images are sensitive to the emission profiles, indicating it is good for study on local emission profiles.



Experimental images measured at the beginning of a discharge



- Plasma expands as the plasma density increases at the startup phase of the discharge.



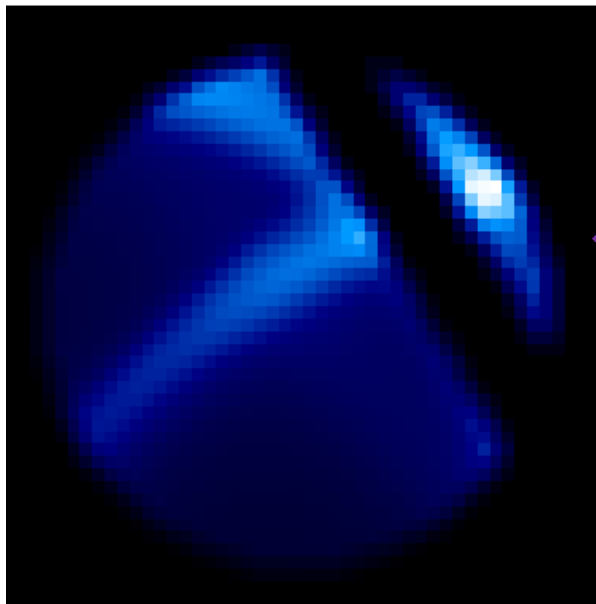
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Numerical tests of computed tomographic reconstruction

Line-integrated image



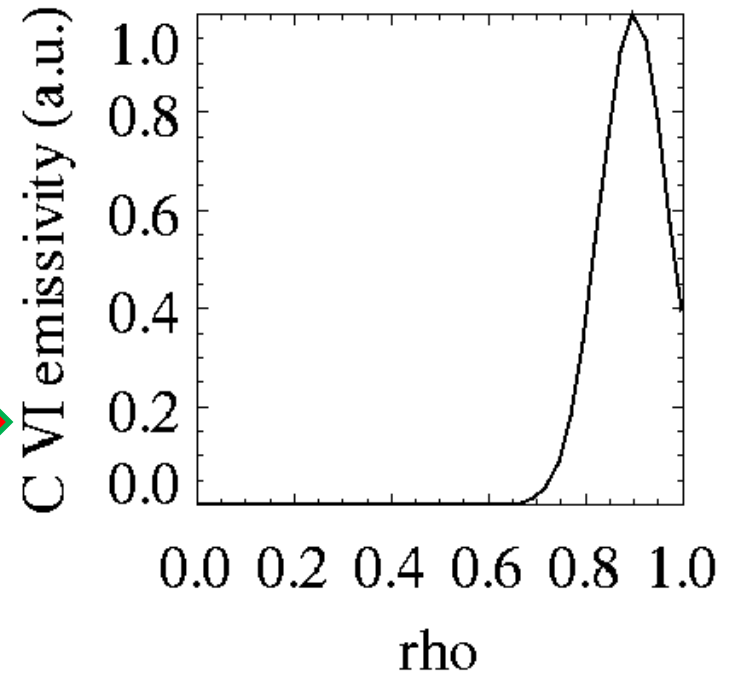
$$\mathbf{I} = \mathbf{S}\mathbf{E}$$

Synthetic image

CT reconstruction



Phantom



- Assuming a certain phantom, synthetic images could be obtained.
- Can the tomographic reconstruction be successfully performed?



Numerical methods for tomographic image reconstruction

- Inverse Radon Transform (Standard Method of CT)
- Starting from the linear equation: $\mathbf{I} = \mathbf{SE}$
 - Model approach
 - Series Expansion Model (Linear, optimized with AIC, eg: Fourier-Bessel)
 - Model-free approach using penalty functions
 - Phillips-Tikhonov (Linear, optimized with GCV)
 - Maximum Entropy, Hopfield Network



Tomographic reconstruction with penalty functions

- If \mathbf{S} is not ill-conditioned, then $\mathbf{E} = (\mathbf{S}^T \mathbf{S})^{-1} \mathbf{S}^T \mathbf{L}$ if $(\mathbf{S}^T \mathbf{S})^{-1}$ exists.
- In tomography (fusion research), Eq.(2) is an ill-conditioned equation.

$$\min. \quad J \equiv \|\mathbf{S}\mathbf{E} - \mathbf{I}\|^2 + \gamma P(E) \quad (3)$$

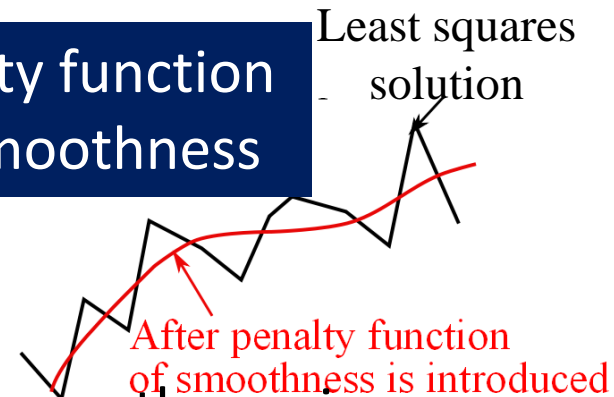
Least squares error

Penalty function of smoothness

Least squares solution

γ is the regularization parameter.

- A minimization of a penalty function $P(E)$ of smoothness is introduced to perform the regularization.
- Several penalty functions are proposed, such as Laplacian, Entropy.





Iwama's type of Phillips-Tikhonov regularization (P-T)

- Linear regularization: $P(E) = \|CE\|^2$

Here, C is the Laplacian operator.

- Solution:

$$E = (S^T S + M\gamma C^T C)^{-1} S^T I$$

After the SV decomposition of matrix $C^{-1}S$ in the form:

$$C^{-1}S = U\Sigma V^T$$

$$\Rightarrow = \sum_{j=1}^M w_j(\gamma) \frac{(I, u_j)}{\sigma_j} C^{-1} v_j$$

$$w_j(\gamma) = 1 / (1 + M\gamma / \sigma_j^2)$$

(N. Iwama et al, Appl. Phys. Lett.54(6) 502 1989)



Comparison of Iwama's P-T and Maximum entropy method (MEM)

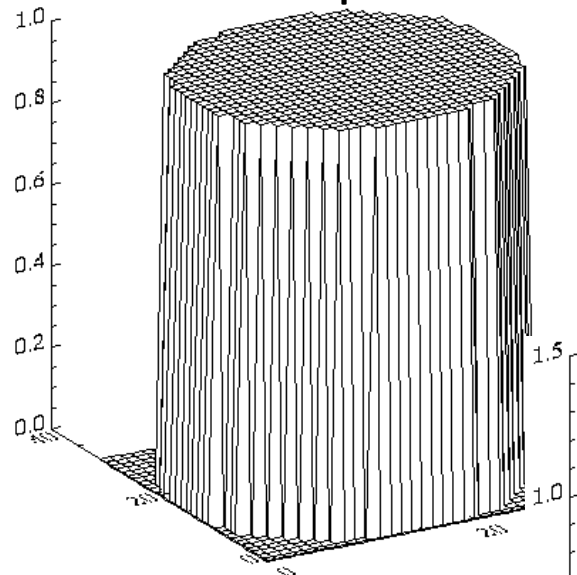
Method	Penalty function	Computing time	Solution
Iwama's P-T	$ \mathbf{CE} ^2$	~ 0.5 min.	Smooth (Negative value may exist)
MEM	$\sum_{k=1}^K E_k \ln E_k$	~ 1 hour	Smoothness is not good (Always nonnegative)

➤ The Iwama's P-T method is selected to investigate the performance of tomographic reconstruction on LHD configuration with phantom tests.



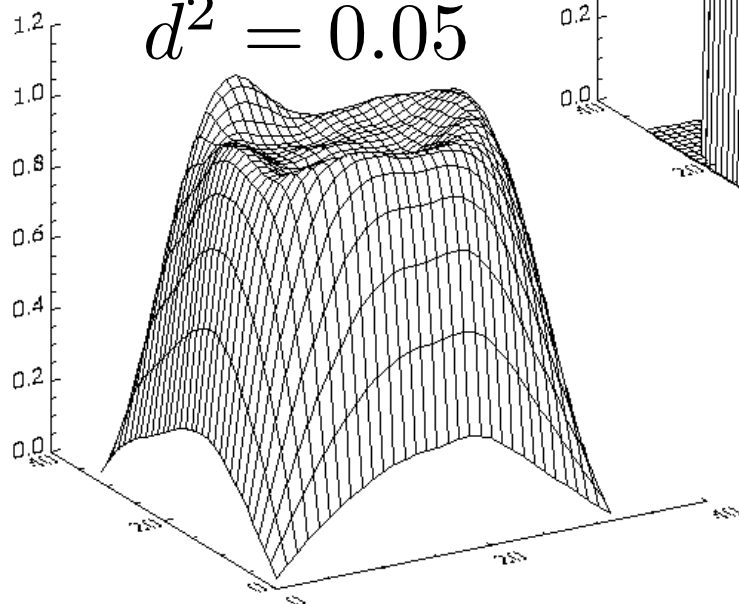
More smooth result can be obtained by Iwama's P-T method

Assumed profile



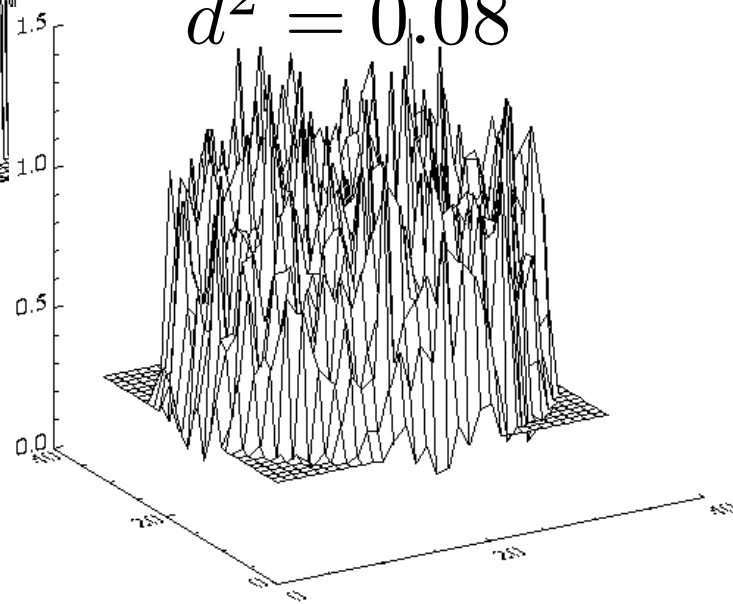
Reconstructed with Iwama's P-T

$$d^2 = 0.05$$



Reconstructed with MEM

$$d^2 = 0.08$$





Determination of the optimized regularization parameter γ

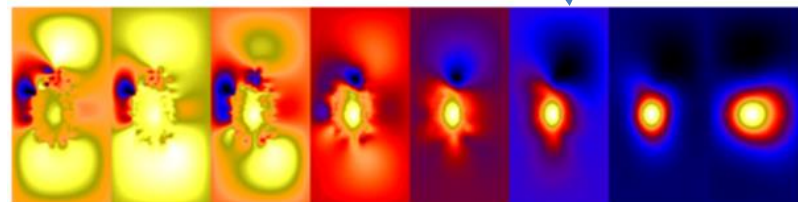
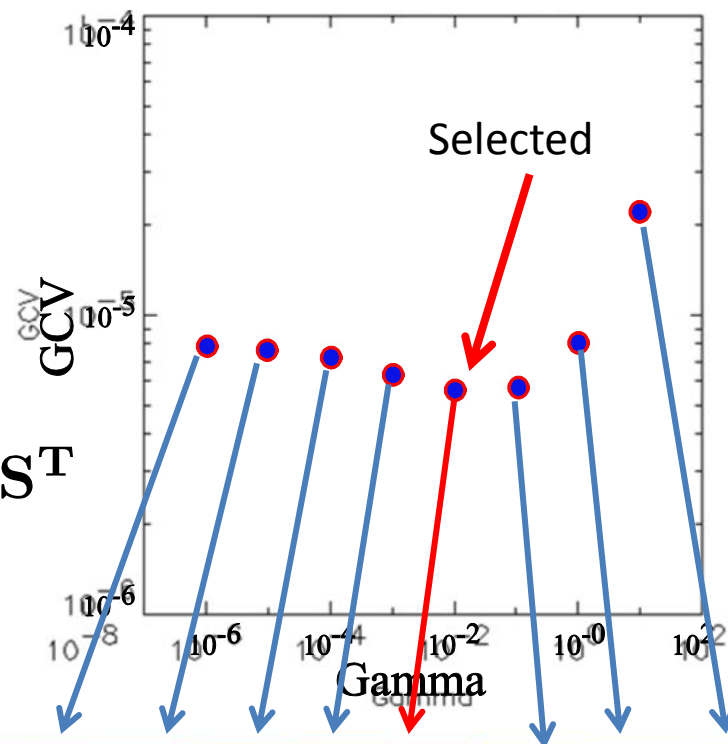
➤ GCV (Generalized Cross Validation) function is defined as:

$$V(\gamma) = \frac{M \|\mathbf{I}_M - \mathbf{A}(\gamma)\mathbf{I}\|^2}{\{\text{Trace}[\mathbf{I}_M - \mathbf{A}(\gamma)]\}}$$

where, $\mathbf{A}(\gamma) = \mathbf{S}(\mathbf{S}^T\mathbf{S} + M\gamma\mathbf{I}_M)^{-1}\mathbf{S}^T$

\mathbf{I}_M is the $M \times M$ identity.

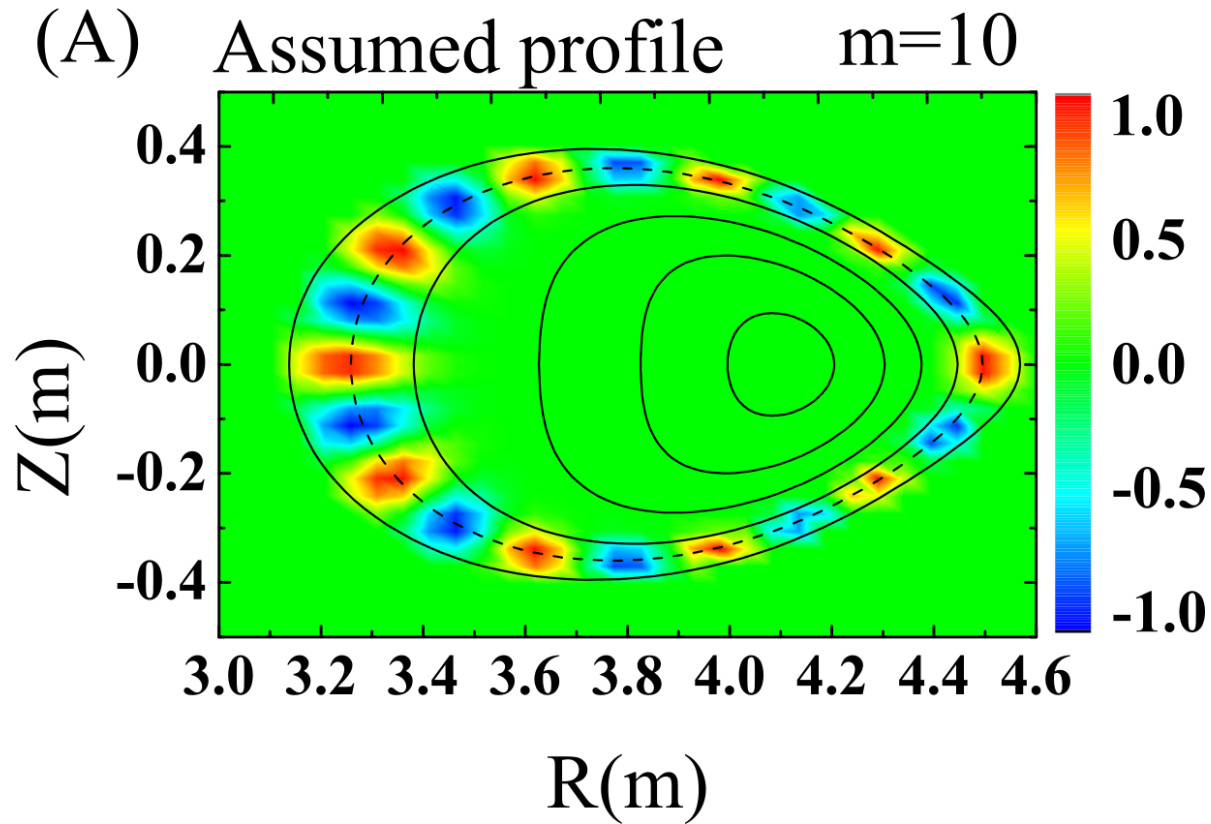
➤ From the information theory, minimum GCV is believed to give an optimum solution.



Preferred fitting ← → Smooth Profile



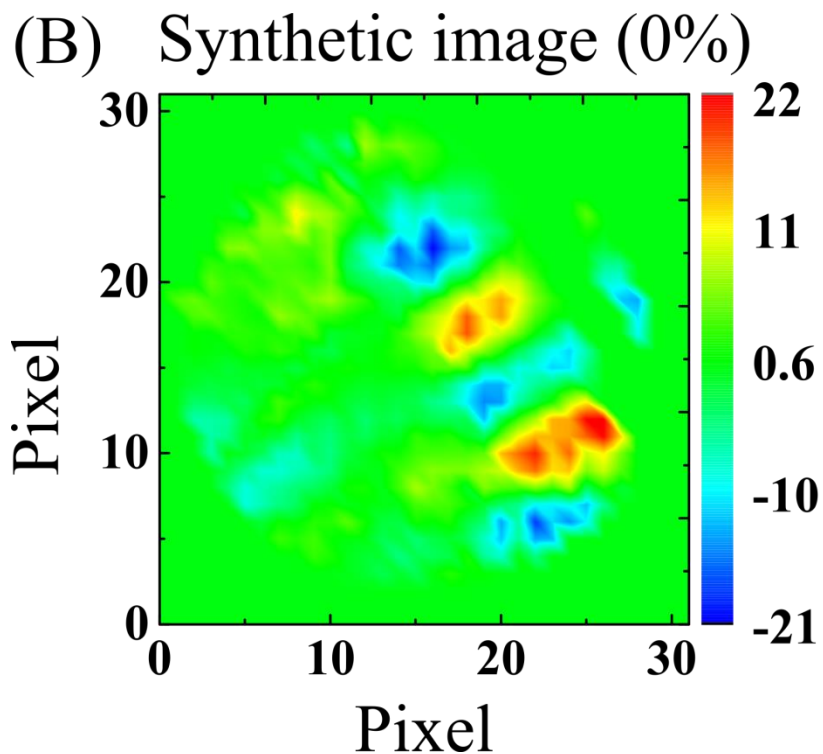
Assumed mode structure



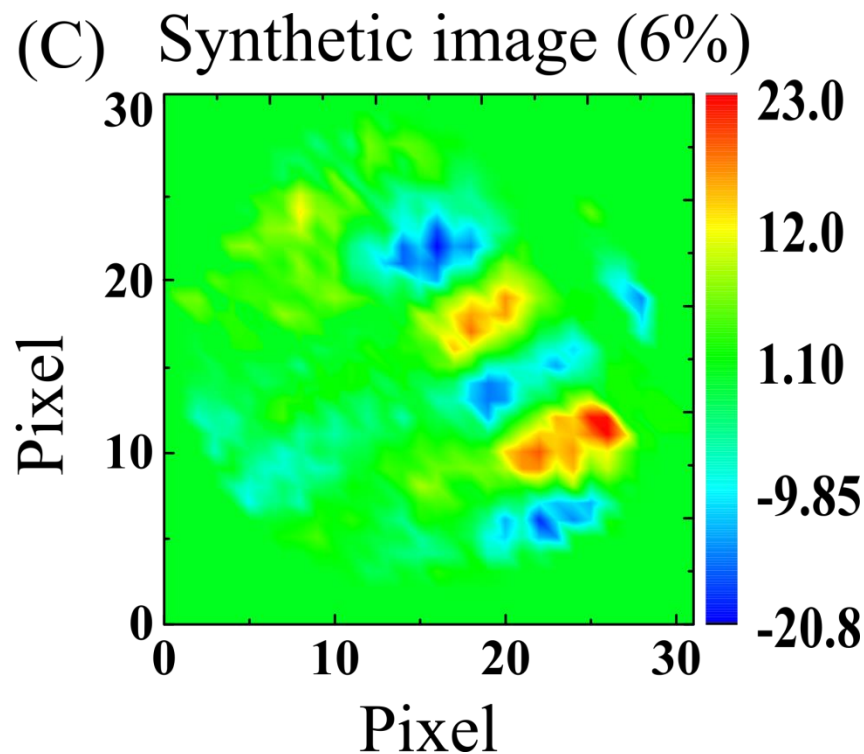


Synthetic images w/wo artificial noise

Without noise



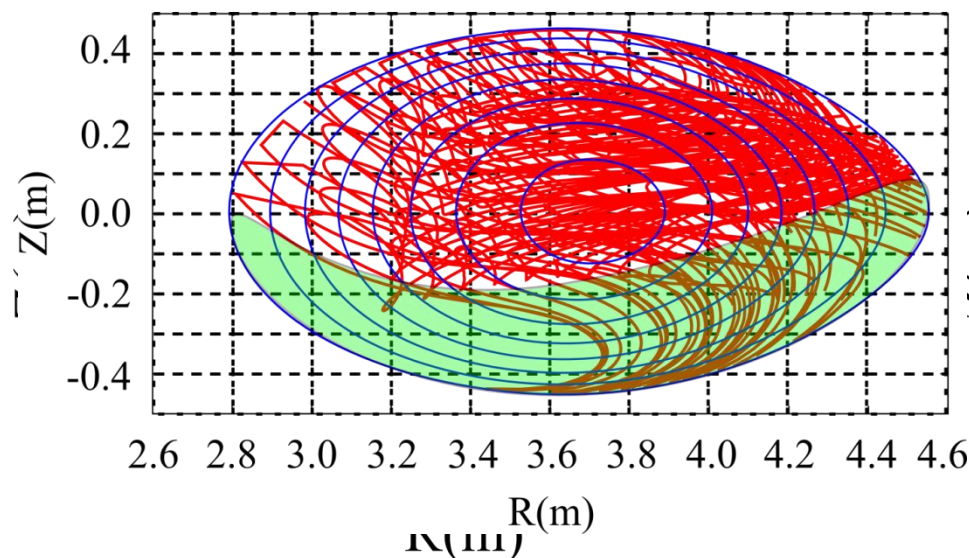
6% noise added



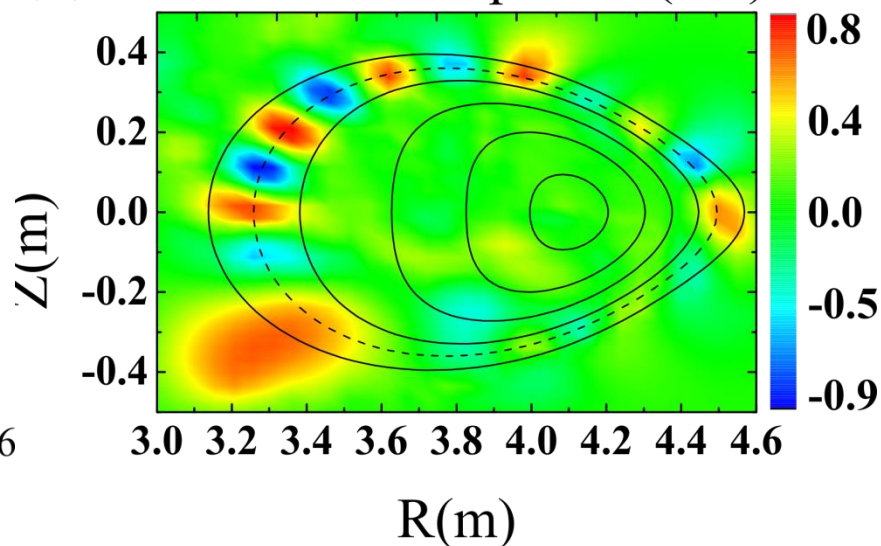


Reconstructed mode structure

Equivalent sightlines on the target plane



(E) Reconstructed profile (6%)



- Mode structure with high mode number can be reconstructed in LHD configuration.
- VUV imaging system can be a potential tool to reconstruct the 2D mode structure with high mode number for LHD plasma in future.

Tingfeng MING, et al, Plasma Fusion Res. 6, 2406120 (2011).



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Emission profiles & line-integrated images

$$E(\rho, \theta) = \exp \left[- \left(\frac{\rho - \rho_p}{w} \right)^2 \right] \cos(m\theta + \phi_0)$$

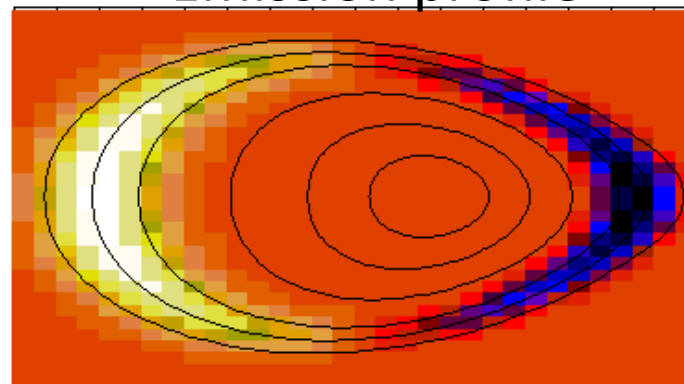
➤ Comparisons of synthetic images and experimental data are performed.

➤ ρ_p, w, m, ϕ_0 are scanned to search the plausible mode structure.

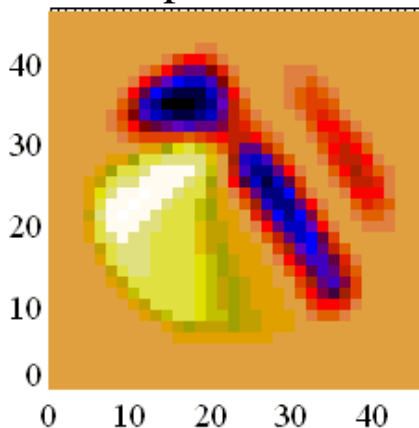
$$d^2 = \frac{1}{N} \sum_n (I_n - I_n^*)^2$$

is defined to clarify the similarity of the synthetic and experimental images.

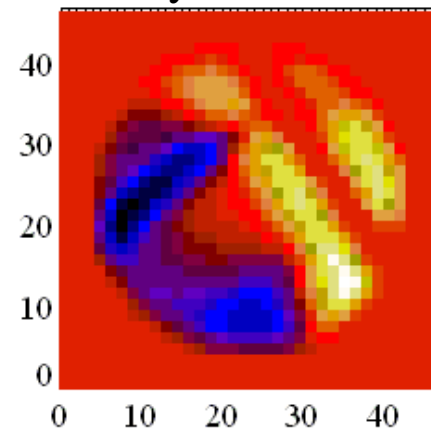
Emission profile



Experimental

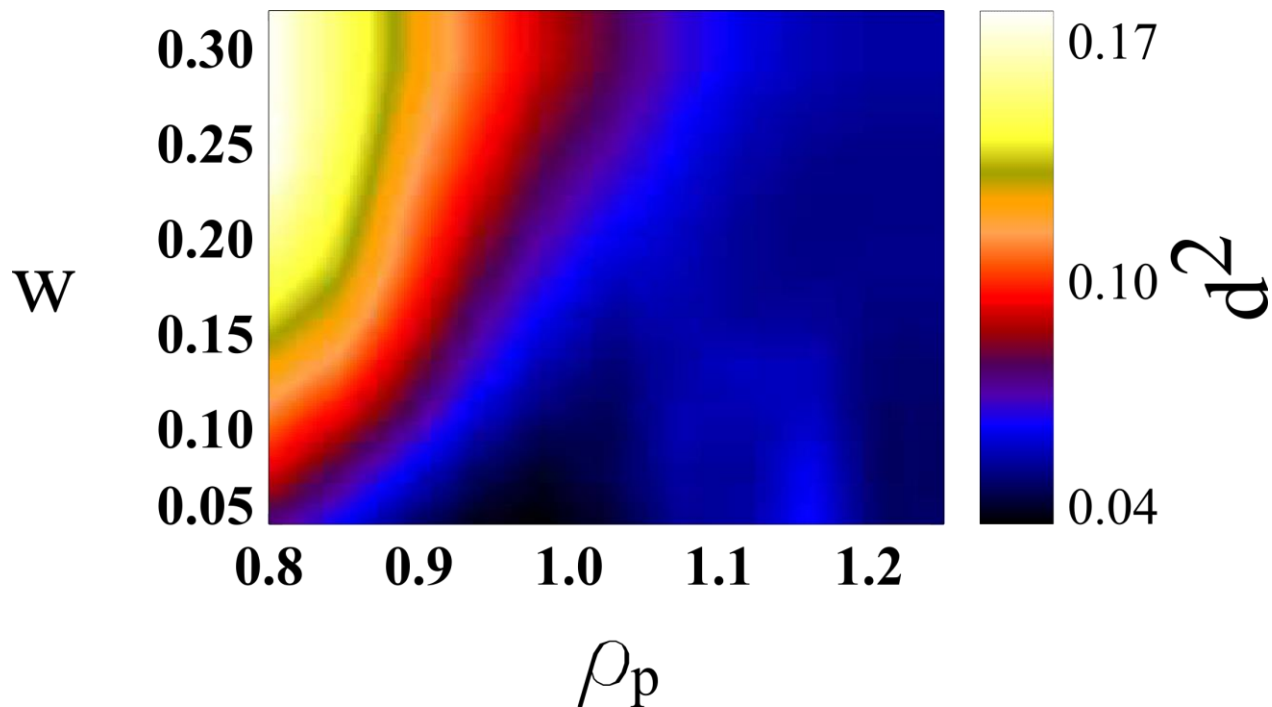


Synthetic





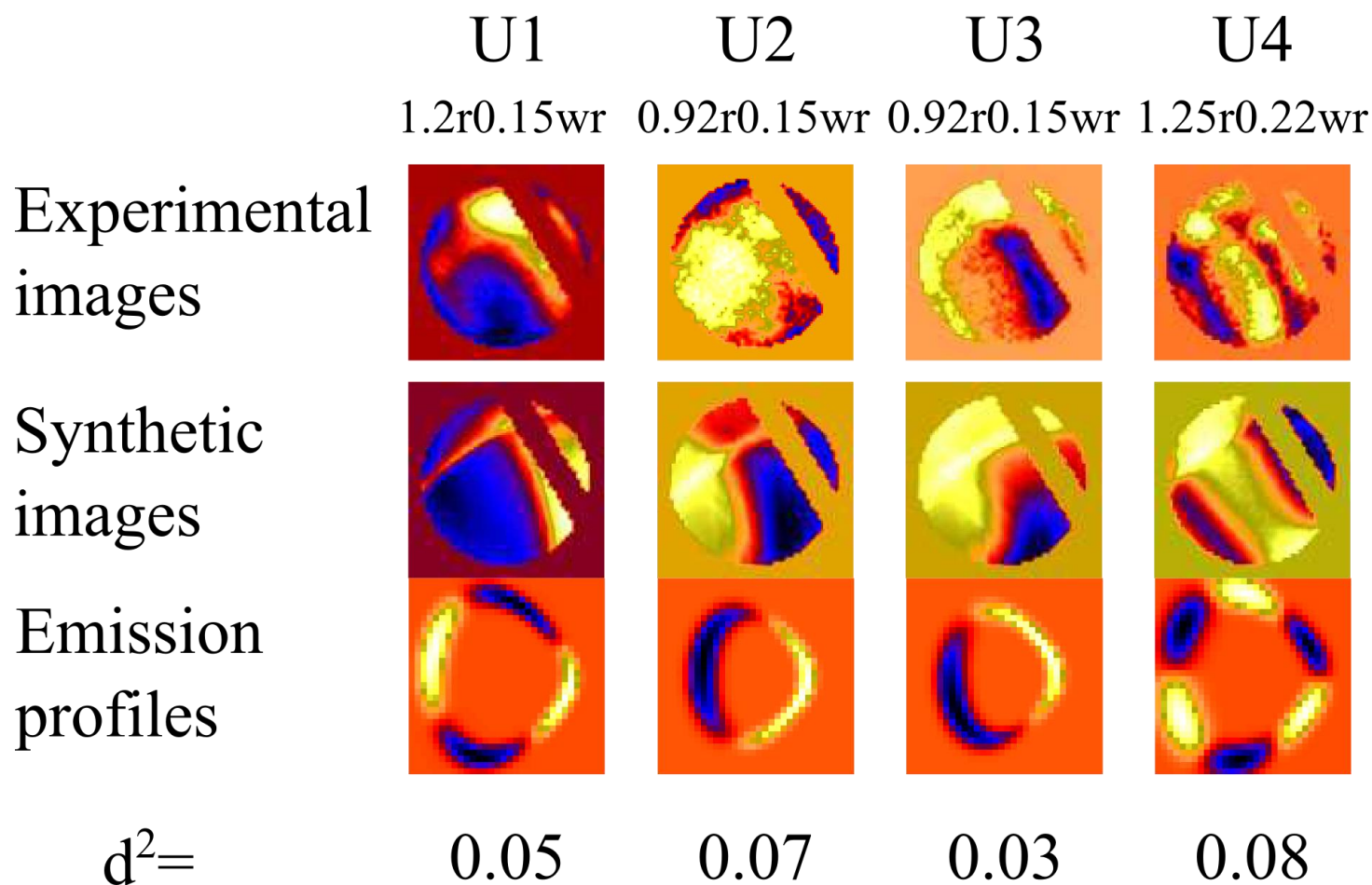
Relative errors



➤ An optimized combination of W and ρ_p gives a minimum d^2 .



Plausible emission profiles estimated from experimental measured images





Summary

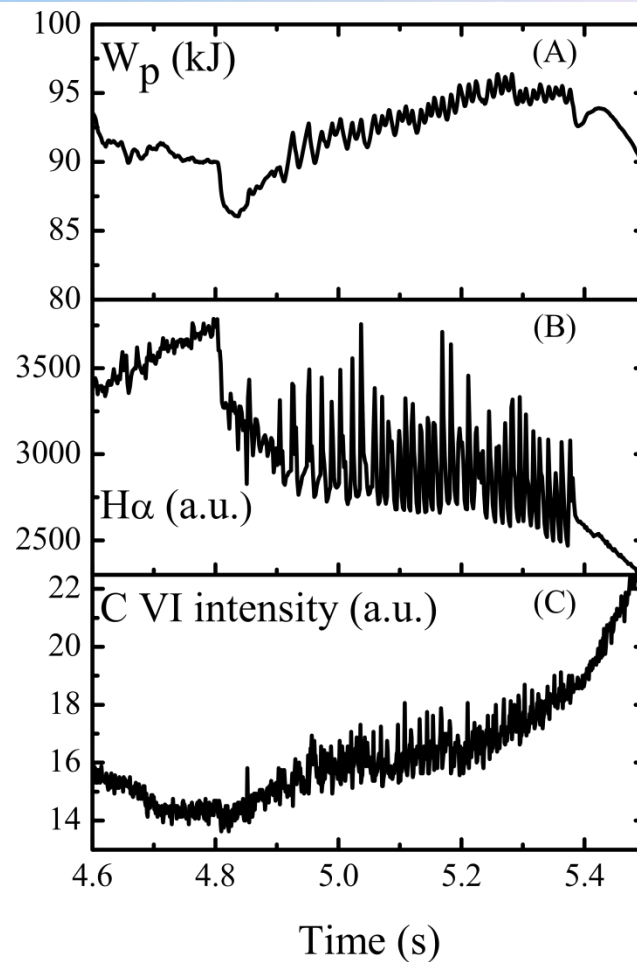
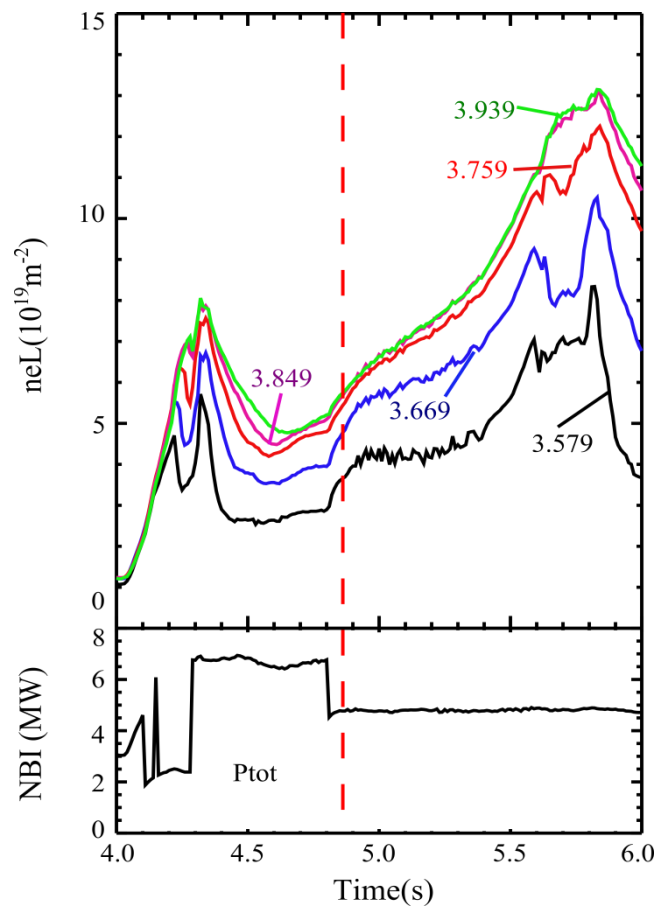
- A new method based on the HINT2 equilibrium code is developed for constructing the geometry matrix for a tangentially viewing imaging system. It can be used with finite beta plasma.
- Numerical tests based on the Iwama's P-T algorithm show that mode structures with **high mode number** can be reconstructed even with a complex shape of LHD plasma. (*Tingfeng MING, et al, Plasma Fusion Res. 6, 2406120 (2011).*)
- Plausible emission profiles caused by ELM crash have been estimated by comparing sythetic images and experimental measurement.



Thank you for your attention!



Observation of the distorted mode structure



($R_{\text{ax}}=3.95\text{m}$, $B_t=-1.0\text{T}$, $\gamma=1.254$)